VEKTORANALYS

Kursvecka 2

LINE INTEGRAL and FLUX INTEGRAL

Kapitel 4-5 Sidor 29-50

TARGET PROBLEM

A person is pushing a mine cart along a path L on a hill.

Calculate the "work" done to move the cart from A to B.



We will arrive to the final answer in two steps:

1- The slope is constant

2- the slope is not constant





$$W = \left| \overline{F}_{g//} \right| \left| \Delta \overline{r} \right| = \left| \overline{F}_{g} \right| \left| \Delta \overline{r} \right| \cos \alpha = \overline{F} \cdot \Delta \overline{r}$$

(to be precise, we should change sign to calculate the work done by the person)

$$W = \sum_{i} W_{i}$$
$$W_{i} \approx \overline{F}(\overline{r_{i}}) \cdot \Delta \overline{r_{i}} \Longrightarrow W \approx \sum_{i} \overline{F}(\overline{r_{i}}) \cdot \Delta \overline{r_{i}}$$

For "very small" segments:

$$W = \lim_{\Delta \overline{r_i} \to 0} \sum_i \overline{F}(\overline{r_i}) \cdot \Delta \overline{r_i} \equiv \int_L \overline{F}(\overline{r}) \cdot d\overline{r}$$

is the line integral of \overline{F} along the path L

We need to:

- introduce a VECTOR FIELD, $\overline{F}(\overline{r})$
- Define the infinitesimal displacement $d\overline{r}$ along the path L

VECTOR FIELD

A vector field associates a vector $\overline{A}(x,y,z)$ to each point (x,y,z) of the space.

Examples: - velocity distribution in a fluid - magnetic field around a magnet - electric field around an electric charge

Two typical ways to represent a vector field:



VECTOR FIELD

The airplane wing example (velocity field of air around a wing)



EXERCISE: 1- plot the vector field $\overline{F}(\overline{r}) = (x, 0)$ 2- write $\overline{F}(\overline{r})$ on the curve defined by: $\overline{r}(u) = (u, u^2)$

$d\overline{r}$ and the line integral



L is described by
$$\overline{r} = \overline{r}(u)$$

$$\overline{r_i} = \overline{r}(u_i)$$

$$\overline{r_{i+1}} = \overline{r}(u_{i+1})$$

$$u_{i+1} = u_i + \Delta u$$

$$\Rightarrow d\overline{r} = \lim_{\Delta u \to 0} \Delta \overline{r_i} = \lim_{\Delta u \to 0} \left[\overline{r}(u_{i+1}) - \overline{r}(u_i) \right] = \lim_{\Delta u \to 0} \frac{\left[\overline{r}(u_{i+1}) - \overline{r}(u_i) \right]}{\Delta u} \Delta u = \frac{d\overline{r}}{du} du$$

So, the line integral can be calculated as:

$$\int_{L} \overline{F}(\overline{r}) \cdot d\overline{r} = \int_{a}^{b} \overline{F}(\overline{r}(u)) \cdot \frac{d\overline{r}}{du} du$$

EXERCISE: Calculate $\int_{L} \overline{F}(\overline{r}) \cdot d\overline{r}$ with $\overline{F}(\overline{r}) = (x,0)$ and L defined by $\overline{r}(u) = (u, u^{2})$ $u: 0 \to 1$

LINE INTEGRAL (some useful properties)



PROOF

If all line elements change sign then also the integral will change sign.

DEFINITION

The line of integral of \overline{A} along a closed curve C is called circulation of a \overline{A} along C:

$$\oint_C \overline{A}(\overline{r}) \cdot d\overline{r}$$

(4)

(3)

LINE INTEGRAL

DEFINITION: A vector field \overline{A} is called <u>conservative</u> if: $\oint_C \overline{A}(\overline{r}) \cdot d\overline{r} = 0$

THEOREM 2 (4.3 in the textbook)

The circulation of \overline{A} along a close curve *C* is zero if and only if for all points P and Q the line integral of \overline{A} from P to Q is independent from the integration path between P and Q.

PROOF

Assume that L_1 and L_2 are two curves from P to Q. Then $L=L_1-L_2$ is a closed curve.

(1) The circulation is zero \Rightarrow the line integral from P to Q is independent from the path

$$\left. \oint_{L} \overline{A}(\overline{r}) \cdot d\overline{r} = 0 \\
\oint_{L} \overline{A}(\overline{r}) \cdot d\overline{r} = \int_{L_{1}-L_{2}} \overline{A}(\overline{r}) \cdot d\overline{r} = \int_{L_{1}} \overline{A}(\overline{r}) \cdot d\overline{r} - \int_{L_{2}} \overline{A}(\overline{r}) \cdot d\overline{r} \right\} \implies \int_{L_{1}} \overline{A}(\overline{r}) \cdot d\overline{r} = \int_{L_{2}} \overline{A}(\overline{r}) \cdot d\overline{r} \\
\xrightarrow{\text{The line integral is independent from the integral is independent integration path!}}$$

(2) The line integral from P to Q is independent from the path \Rightarrow the circulation is zero.

$$\int_{L_1} \overline{A}(\overline{r}) \cdot d\overline{r} = \int_{L_2} \overline{A}(\overline{r}) \cdot d\overline{r}$$

$$\oint_L \overline{A}(\overline{r}) \cdot d\overline{r} = \int_{L_1-L_2} \overline{A}(\overline{r}) \cdot d\overline{r} = \int_{L_1} \overline{A}(\overline{r}) \cdot d\overline{r} - \int_{L_2} \overline{A}(\overline{r}) \cdot d\overline{r}$$

$$\Rightarrow \quad \oint_L \overline{A}(\overline{r}) \cdot d\overline{r} = 0$$

$$\text{The circulation is zero}$$

LINE INTEGRAL

THEOREM 3 (4.4 in the textbook)

If $\overline{A} = grad\phi$: $\int_{P}^{Q} \overline{A}(r) \cdot d\overline{r} = \phi(Q) - \phi(P)$

> So the line integral is independent from the integration path and depends only on the starting point and on the ending point

PROOF

If $\overline{r}(u)$ is a curve from P to Q then, using the chain rule for the partial derivative:

$$\int_{\overline{r}(u)} \overline{A}(\overline{r}) \cdot d\overline{r} = \int_{p}^{q} \operatorname{grad} \phi \cdot \frac{d\overline{r}}{du} du = \int_{p}^{q} \left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right) \cdot \left(\frac{dx}{du}, \frac{dy}{du}, \frac{dz}{du} \right) du =$$
$$= \int_{p}^{q} \left(\frac{\partial \phi}{\partial x} \frac{dx}{du} + \frac{\partial \phi}{\partial y} \frac{dy}{du} + \frac{\partial \phi}{\partial z} \frac{dz}{du} \right) du = \int_{p}^{q} \frac{d}{du} \phi(\overline{r}(u)) du = \phi(Q) - \phi(P)$$

Or, easier:
$$\int_{L} \overline{A}(\overline{r}) \cdot d\overline{r} = \int_{L} grad\phi \cdot d\overline{r} = \int_{L} d\phi = \phi(B) - \phi(A)$$

(5)

OTHER KINDS OF LINE INTEGRALS

- It is possible to combine scalar and vector line elements in many different ways along a curve L and thus get different kinds of line integrals
- Some examples:

$$\int_{L}^{L} \phi(\overline{r}) d\overline{r}$$
$$\int_{L} A(\overline{r}) \times d\overline{r}$$

 $\oint \phi(\overline{r}) ds$

where $d\overline{r} = \hat{e}ds$

(8)

(7)

(6)

• To calculate the integrals:

$$\overline{r} \to \overline{r}(u)$$

$$L \to [a,b] \quad where \ u : a \to b$$

$$d\overline{r} = \frac{d\overline{r}}{du} du \quad or \quad ds = \left|\frac{d\overline{r}}{du}\right| du$$

The force is: $\overline{F} = (-yz, xz, -1)$

The path is L: $\overline{r} = (\cos u, \sin u, u)$ with $u: 0 \to 4\pi$ Calculate the work from P=(1,0,0) till Q=(1,0,4\pi)



$$W = \int_{L} \overline{F}(\overline{r}) \cdot d\overline{r} = \int_{a=0}^{b=4\pi} \overline{F}(\overline{r}(u)) \frac{d\overline{r}}{du} du$$



$$\frac{\overline{F}(\overline{r}(u)) = (-(\sin u)u, (\cos u)u, -1)}{\frac{d\overline{r}}{du} = (-\sin u, \cos u, 1)} \Rightarrow \overline{F}(\overline{r}(u)) \cdot \frac{d\overline{r}}{du} = (u\sin^2 u + u\cos^2 u - 1) = u(\sin^2 u + \cos^2 u) - 1 = u - 1$$

$$W = \int_{L} \overline{F}(\overline{r}) \cdot d\overline{r} = \int_{0}^{4\pi} (u-1) du = \left[\frac{u^{2}}{2} - u\right]_{0}^{4\pi} = 8\pi^{2} - 4\pi$$

PRACTICAL EXAMPLE: THE BIOT-SAVART LAW

The magnetic field in a point P of a steady line current is given by the Biot-Savart law:

Х

$$\overline{B}(\overline{\mathbf{r}}) = \frac{\mu_0 I}{4\pi} \int_L \frac{d\overline{l} \, \left| \times \left(\overline{r} - \overline{r} \right) \right|}{\left| \overline{r} - \overline{r} \right|^3}$$

Where $d\overline{l}$ ' is an infinitesimal length along the wire,

 $\overline{r}\,$ is the position vector of the point P and

 \overline{r} ' is a vector from the origin to $d\overline{l}$ '

Therefore, $\overline{r} - \overline{r}'$ is a vector from $d\overline{l}'$ to P



PRACTICAL EXAMPLE: THE BIOT-SAVART LAW

The magnetic field in a point P of a steady line current is given by the Biot-Savart law:



WHICH STATEMENT IS WRONG?

1- The image area of a vector field \overline{A} is composed of vectors (yellow)

- 2- The line integral $\int \overline{F} \cdot d\overline{r}$ is a scalar (red)
- 3- The sign of the line integral $\int \overline{F} \cdot d\overline{r}$ depends

on the integration path

(green)

4- The gradient of a vector field can be written as: grad \overline{A} (blue)

TARGET PROBLEM

We are making cranberry juice. After cranberries are squeezed, It is better to filter the juice!

How much juice flows trough the cloth each second?

We need :

(1) to understand how to calculate the **flux** of a **VECTOR FIELD** $\overline{v}(x, y, z)$

(2) a method to integrate the flux over the whole surface.



THE FLUX

In the juice example, the flux F is the volume of the fluid ΔV that flows through the surface in the time Δt .

 $F = \frac{\Delta V}{\Delta t}$

STEP 1: - the fluid velocity is perpendicular to the surface

- the surface is not curved

$$\Delta V = x\Delta S = \left|\overline{v}\right| \Delta t\Delta S$$
$$F = \frac{\Delta V}{\Delta t} = \left|\overline{v}\right| \Delta S$$



STEP 3: - the surface is curved

$$F = \sum_{i} F_{i} = \lim_{\Delta S_{i} \to 0} \sum_{i} \overline{v}_{i} \cdot \Delta \overline{S}_{i} \equiv \int_{S} \overline{v} \cdot d\overline{S}$$

 $\left| \overline{v} \cdot d\overline{S} \right|$ is the flux integral of \overline{v} on the surface S







$d\overline{S}$ and flux integral

• Assume that the surface S is parameterized by $\bar{r} = \bar{r}(u, v)$



The area ΔS is $\Delta S = |\Delta \overline{r_2}| \sin \alpha |\Delta \overline{r_1}| = |\Delta \overline{r_1} \times \Delta \overline{r_2}|$

 \hat{n} is perpendicular to S. But also $\Delta \overline{r_1} \times \Delta \overline{r_2}$ is perpendicular to S

$$\Rightarrow \Delta \overline{S} = \hat{n} \Delta S = \Delta \overline{r_1} \times \Delta \overline{r_2}$$

$d\overline{S}$ and flux integral

$$d\overline{S} = \lim_{\Delta u \to 0} \Delta \overline{S} = \lim_{\Delta u \to 0} \Delta \overline{r}_{1} \times \Delta \overline{r}_{2}$$

$$d\overline{r}_{1} = \lim_{\Delta u \to 0} \Delta \overline{r}_{1} = \lim_{\Delta u \to 0} \overline{r}(u + \Delta u, v) - \overline{r}(u, v) =$$

$$= \lim_{\Delta u \to 0} \frac{\overline{r}(u + \Delta u, v) - \overline{r}(u, v)}{\Delta u} \Delta u = \frac{\partial \overline{r}(u, v)}{\partial u} du \Rightarrow d\overline{S} = \frac{\partial \overline{r}}{\partial u} \times \frac{\partial \overline{r}}{\partial v} du dv$$

in the same way:

$$d\overline{r}_2 = \frac{\partial \overline{r}(u,v)}{\partial v} dv$$

So, the flux integral of the vector field \overline{v} on the surface \overline{S} can be calculated as:

$$\int_{S} \overline{v} \cdot d\overline{S} = \int_{u} \int_{v} \overline{v} \left(\overline{r}(u, v) \right) \cdot \left(\frac{\partial \overline{r}}{\partial u} \times \frac{\partial \overline{r}}{\partial v} \right) du dv$$



Parameterization of \overline{S} $z=x^2+y^2$ $x^2+y^2 \le 1$



Parameterization of the vector field: $\overline{A} = (xy, 0, z^2) = (\rho^2 \sin \varphi \cos \varphi, 0, \rho^4)$

Flux calculation using equation 10

$$\begin{split} & \iint_{S} \overline{A} \cdot d\overline{S} = \iint_{S} \overline{A}(\overline{r}(\rho, \varphi)) \cdot \left(\frac{\partial \overline{r}}{\partial \rho} \times \frac{\partial \overline{r}}{\partial \varphi}\right) d\rho d\varphi \\ & \frac{\partial \overline{r}}{\partial \rho} = \left(\cos\varphi, \sin\varphi, 2\rho\right) \\ & \frac{\partial \overline{r}}{\partial \varphi} = \left(-\rho \sin\varphi, \rho \cos\varphi, 0\right) \end{split} \right\} \Rightarrow \left(\frac{\partial \overline{r}}{\partial \rho} \times \frac{\partial \overline{r}}{\partial \varphi}\right) = \begin{vmatrix} \hat{e}_{x} & \hat{e}_{y} & \hat{e}_{z} \\ \cos\varphi & \sin\varphi & 2\rho \\ -\rho \sin\varphi & \rho \cos\varphi & 0 \end{vmatrix} = \\ & (-2\rho^{2}\cos\varphi, -2\rho^{2}\sin\varphi, \rho \cos^{2}\varphi + \rho \sin^{2}\varphi) = \\ & (-2\rho^{2}\cos\varphi, -2\rho^{2}\sin\varphi, \rho) \end{aligned}$$

Note that $\left(\frac{\partial \overline{r}}{\partial \rho} \times \frac{\partial \overline{r}}{\partial \varphi}\right)$ has a positive z-component, while the flux was in the other direction.

So we ordinary solve the integral but then we change the sign in the answer!

$$\iint_{-S} \overline{A} \cdot d\overline{S} = \iint_{-S} \overline{A}(\overline{r}(\rho, \varphi)) \cdot \left(\frac{\partial \overline{r}}{\partial \rho} \times \frac{\partial \overline{r}}{\partial \varphi}\right) d\rho d\varphi =$$

$$\int_{0}^{2\pi} \int_{0}^{1} \left(\rho^{2} \sin\varphi \cos\varphi, 0, \rho^{4}\right) \cdot (-2\rho^{2} \cos\varphi, -2\rho^{2} \sin\varphi, \rho) d\rho d\varphi =$$

$$\int_{0}^{2\pi} \int_{0}^{1} \left(-2\rho^{4} \sin\varphi \cos^{2}\varphi + 0 + \rho^{5}\right) d\rho d\varphi =$$

$$\int_{0}^{2\pi} \left[-\frac{2}{5}\rho^{5} \sin\varphi \cos^{2}\varphi + \frac{1}{6}\rho^{6}\right]_{0}^{1} d\varphi = \int_{0}^{2\pi} \left(-\frac{2}{5}\sin\varphi \cos^{2}\varphi + \frac{1}{6}\right) d\varphi =$$

$$\left[-\frac{2}{5}\left(-\frac{\cos^{3}\varphi}{3}\right) + \frac{1}{6}\varphi\right]_{0}^{2\pi} = \frac{\pi}{3}$$

But we must change sign! The answer is $-\frac{\pi}{3}$

WHICH STATEMENT IS WRONG?

1- The flux integral is a scalar

(yellow)

2- Flux integrals can be calculated also on a closed surface. (red)

- 3- The perpendicular to the integration surface points out from an arbitrary side. (green)
- 4- The flux through a membrane can be calculated with flux integrals.

(blue)