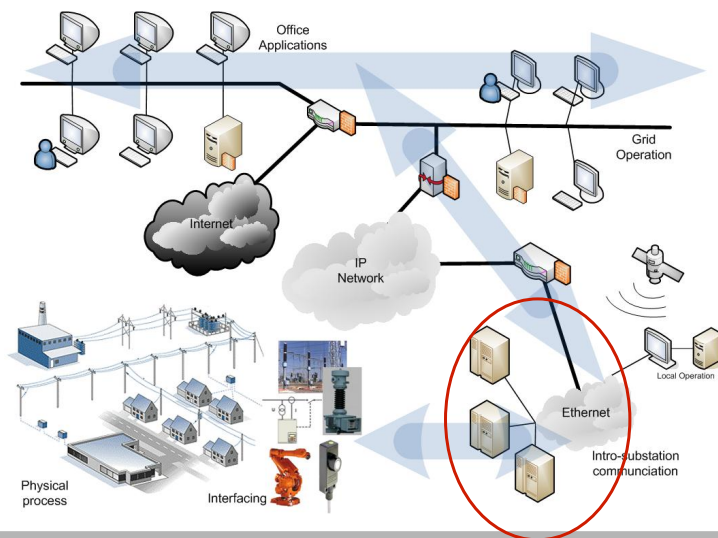




# Lecture 5a Substation Automation Systems

## Course map





## Contents of the Lecture

- Part 1 – Substation Automation
  - Substation Automation Development
  - Substation Automation Architectures
- Part 2 – IEC 61850 Standard
  - Purpose & Scope of IEC 61850
  - The Information Model in 61850
  - Substation Communication (intro)
  - Device Configuration & Example

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## Part 1 Substation Automation

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## Local systems



RTU - Remote Terminal Units  
PLC - Programmable Logic Controllers  
IED - Intelligent Electronic Devices  
...



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## Programmable controllers

PLC programming



- Automation of electromechanical processes
- Built for tough environments
- Hard real-time system – outputs in bounded time
- Fairly simple and cheap devices.



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# Substation automation

## Common components

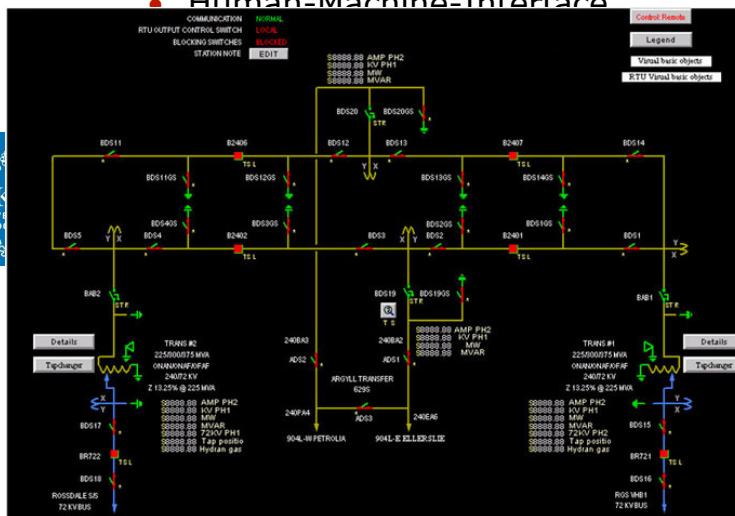
- Intelligent Electronic Device (IED)
  - Digital protective relay with added functionality
  - Can usually interface with RTU
    - Report events and measurement data
    - Receive commands from RTU/SCADA
  - Advanced functions need IEDs to communicate with each other
    - Horizontal communication
  - Control functions can include
    - Load tap changer controller
    - CB controller
    - Capacitor bank switches
    - Recloser controllers
    - Voltage regulators



# Substation automation

## Common components

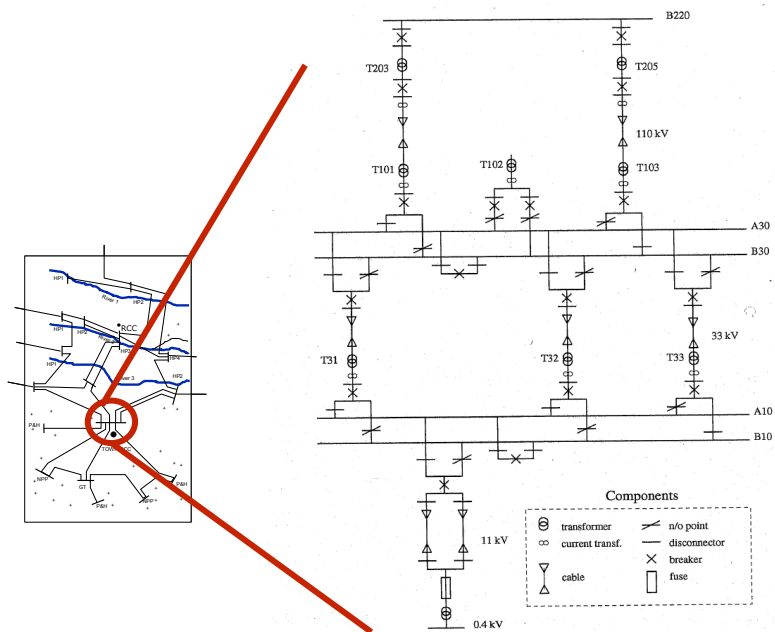
- Human-Machine-Interface



# Terminology



- The terminology used for describing devices and Architectures varies significantly across vendors as well as with age and size of a particular substation
- For instance, see the difference between Strauss chapter 1 and NPAG chapter 24.
- Here we will use three different terms:
  - Station Controller, the top level controller in a substation
  - Bay controller, the unit controlling a bay in a substation
  - Relay, at the lowest level controlling a single object
- All of these controllers are implemented in IEDs – Intelligent Electronic Devices

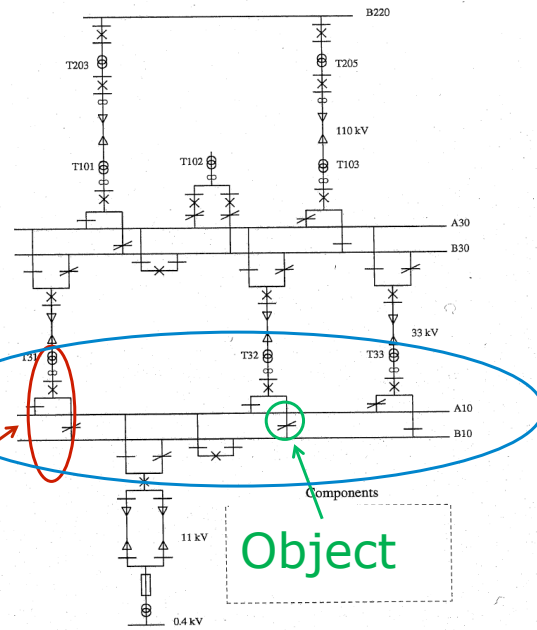




Station

Bay

Object



## What do we want to automate?

Functional area	Functionality			
Interlocking	CB's	Isolators	Contactors	
Tripping sequences	CB failure	Intertripping		Simultaneous trips
Switching sequences	Automatic transformer changeover	Automatic busbar changeover	Restoration of supply following fault	Network re-configuration
Load management	Load shedding	Load restoration	Generator despatch	
Transformer supervision	OLTC control	Load management		
Energy monitoring	Import/export control	Energy management	Power factor control	
Switchgear monitoring	AIS monitoring	GIS monitoring		
Equipment status	Relay status	CB status	Isolator status	
Parameter setting	Relays	Transformers	Switching sequences	IED configuration
HMI functionality	Access control	One-line views	System views	Event logging
	Trend curves	Harmonic analysis	Remote access	Disturbance analysis
	Interface to SCADA	Alarm processing	512	

Table 24.6: Typical substation automation functionality

- Different areas of automation that can be built into a Substation Automation System

## Interlocking



- To ensure that operation of Switchgear is safe and in accordance with standards
- For instance preventing of moving of a disconnecter carrying load
- Implemented as functions in a bay Controller that controls the switchgear in the bay.

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## Switching Sequences



- To ensure that switching operations are performed in a correct sequence, and to automate manual work
- For example, transferring a feeder from one bar to another. Restoration after a fault
- Implemented in station or bay controller depending on scope of the sequence

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## Load Management



- Automation shedding of load, and restoration of load.
- For example as a result of under frequency conditions, feeders are disconnected.
- Implemented at station level control

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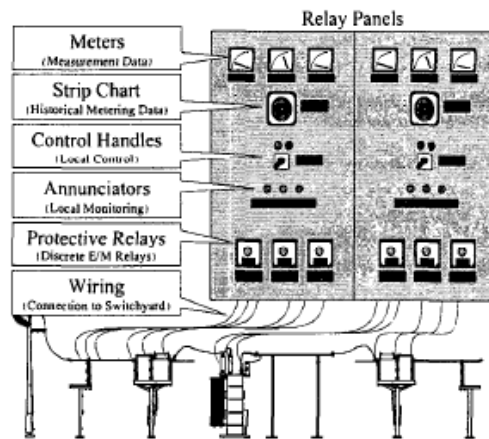
## Equipment Status



- Monitoring of Equipment status for maintenance and safety purposes
- Generate Alarms and events in the case of deterioration or faults
- For example, monitoring of SF6 status, transformer temperatures etc.

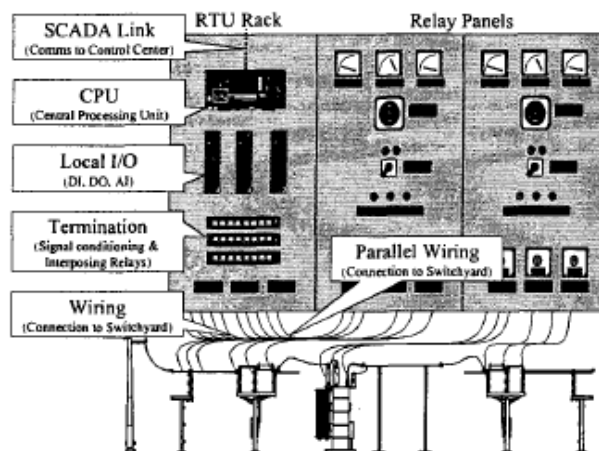
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## Historical Substation design



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## Enter SCADA & RTU

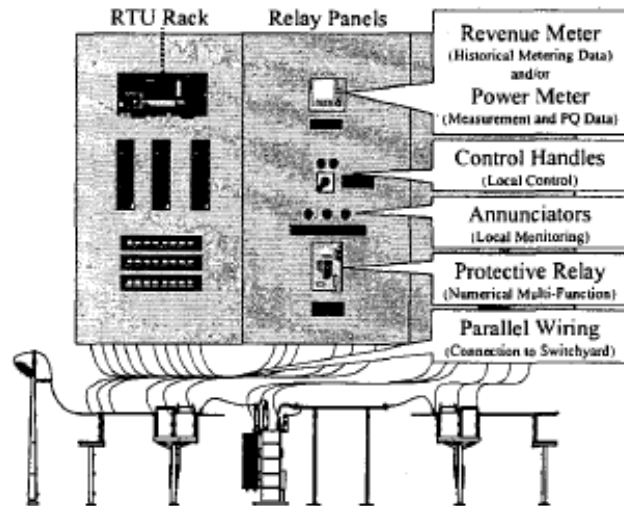


Mathias Ekstedt

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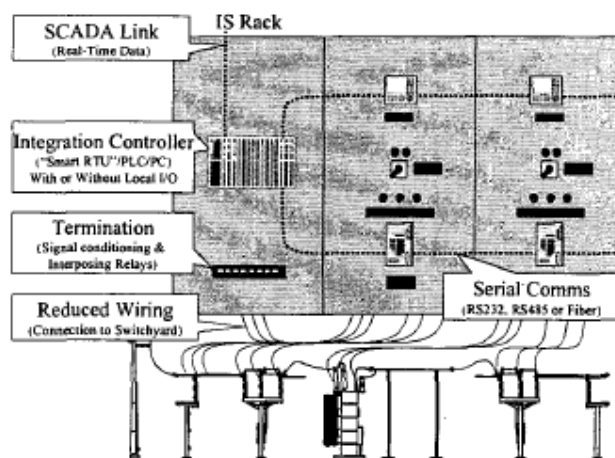
## Enter the IED



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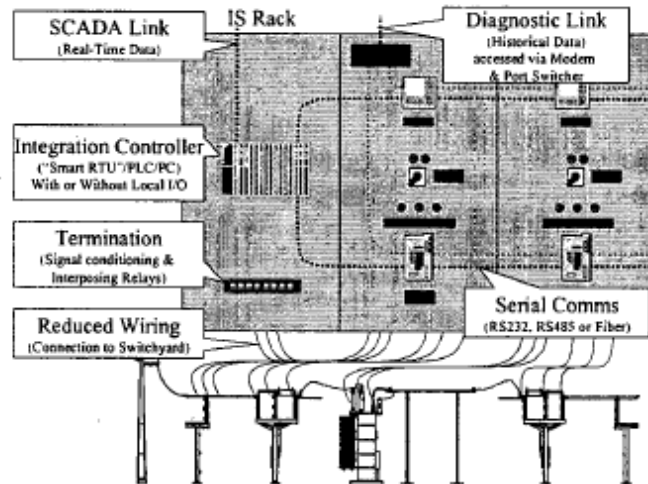
## Integrating RTU with IED



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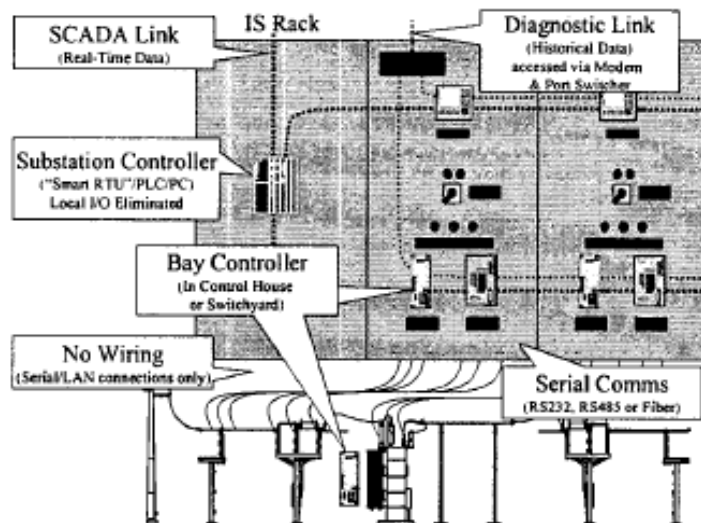
## Addressing Maintenance needs



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## The Bay controller concept



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## Components in a modern SAS

- Intelligent Electronic Device(s)
  - Device that implements functions in a substation, such as a protection relay
- Bay controller
  - A device that controls all devices related to a single bay (transformer, feeder,..) and communicates with relays for functionality
- Human Machine Interface
  - Typically a industry PC with operator console for local control and system configuration
- Communication bus(es)
  - Connection between devices
- Upwards communication interface.
  - Implemented in the HMI, the Bay controller or in an IED.

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## Basic SAS Architectures - 1

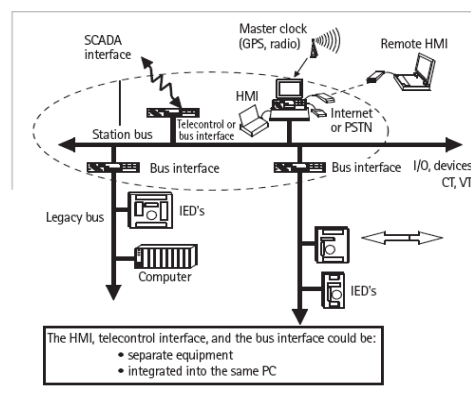


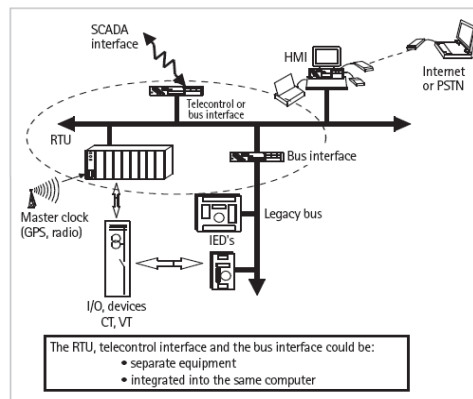
Figure 24.2: HMI-based hardware topology

- **HMI based**
- The Man machine interface (rugged PC) implements all control and communication functionality
- IEDs implement protection & switching functionality
- Simplest solution
- Reliability of HMI computer a risk

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## Basic SAS Architectures - 2



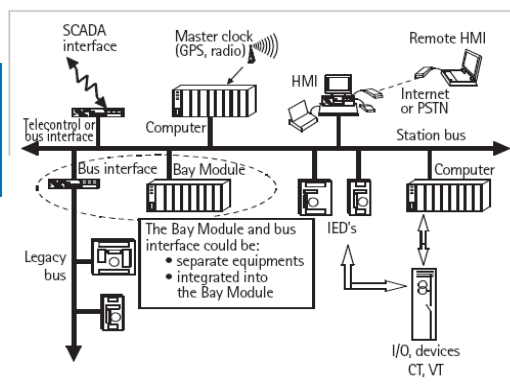
- RTU based
- HMI separated from control & communication
- RTU implements the SCADA interface and substation control
- IEDs implement control & switching functionality

Figure 24.3: RTU-based topology

• *Strauss Type 3 & 4, with telecontrol equipment separate or not*



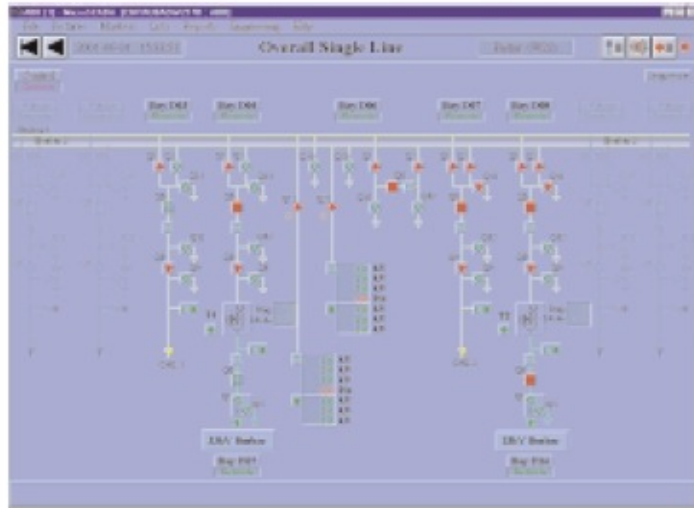
## Basic SAS Architectures - 3



- **Distributed**
- Bay controllers implement interlocking and interface IEDs
- IEDs implement protection and switching
- HMI allows local control and system configuration
- Station controller manages station level control and communicates with SCADA.

Figure 24.4: Decentralised topology

## Man Machine Interface



Local Control & monitoring

## Man Machine Interface



Parameter Name	IED Value	FC Value	Unit	Min	Max
Operation	On				
Base	3000	A	L		9999
OperationOn	Forward				
IL	30,00	ch/tp	0,50		3000,00
RI	5,00	ch/tp	0,10		1000,00
RO	100,00	ch/tp	0,50		3000,00
RII	47,00	ch/tp	0,50		3000,00
RPII	100,00	ch/tp	1,00		3000,00
RPIE	100,00	ch/tp	1,00		3000,00
OperationPP	On				
TimerIPP	On				
IPP	0,000	s		0,000	60,000
OperationPE	On				
TimerPE	On				
PE	0,000	s		0,000	60,000
IPInCP	20	%B		10	30
IPInCPE	20	%B		10	30
IPInCPH	5	%B		5	30

Parameter Setting

## System Configuration



- Substation Automation Systems can have several 10s to 100 different programmable devices.
- Managing functionality & data spread over several platforms becomes a challenging task.
- Consider also that systems from separate vendors often are used.
- Cost of an SAS is not driven by hardware but rather by configuration work!!

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## Substation automation

### Configuration



- Substation Automation Systems can have several *10s to 100* different programmable devices.
- Managing functionality & data spread over several platforms becomes a challenging task.
- Consider also that systems from separate vendors often are used.
- Cost of a SAS is not driven by hardware but rather by configuration work!!

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# Substation automation



Screenshot of a software interface for substation automation. The window title is 'B:\Local Server\IED670 DEMO(2) - PCM 600'. The interface shows a project structure on the left and a parameter settings table on the right.

**Parameter Settings Table:**

Group / Parameter Name	IED Value	PC Value	Unit	Min	Max
Operation	On				
IBase	3000		A	1	9999
OperationDir	Forward				
IL	30,00		ohm/p	0,50	3000,00
RI	5,00		ohm/p	0,10	1000,00
IO	100,00		ohm/p	0,50	9000,00
RO	47,00		ohm/p	0,50	3000,00
RFFP	30,00		ohm/l	1,00	3000,00
RFFE	100,00		ohm/l	1,00	9000,00
OperationPP	On				
Timer RFP	On				
IPP	0,000	s		0,000	60,000
OperationPE	On				
Timer PPE	On				
IFE	0,000	s		0,000	60,000
IRInOpFP	20	%IB		10	30
IRInOpFE	20	%IB		10	30
IRInOpPI	5	%IB		5	30

## Conclusions

Many questions to try and answer...



- How do we organize/label/handle/process the data and commands?
- How are automation and protection applications implemented in these devices?
- What semantics and protocols do devices like IEDs and RTUs use to communicate?
- What standards are used in industry and how do they work?



## Conclusions

- SAS is one of many types of automation systems
- They can be implemented using:
  - Microcontrollers
  - Embedded systems
  - Industrial PCs
- We've looked at some SAS architectures
  - They can vary considerably
- The volume of process data and commands quickly becomes large, this makes management and configuration a complex task

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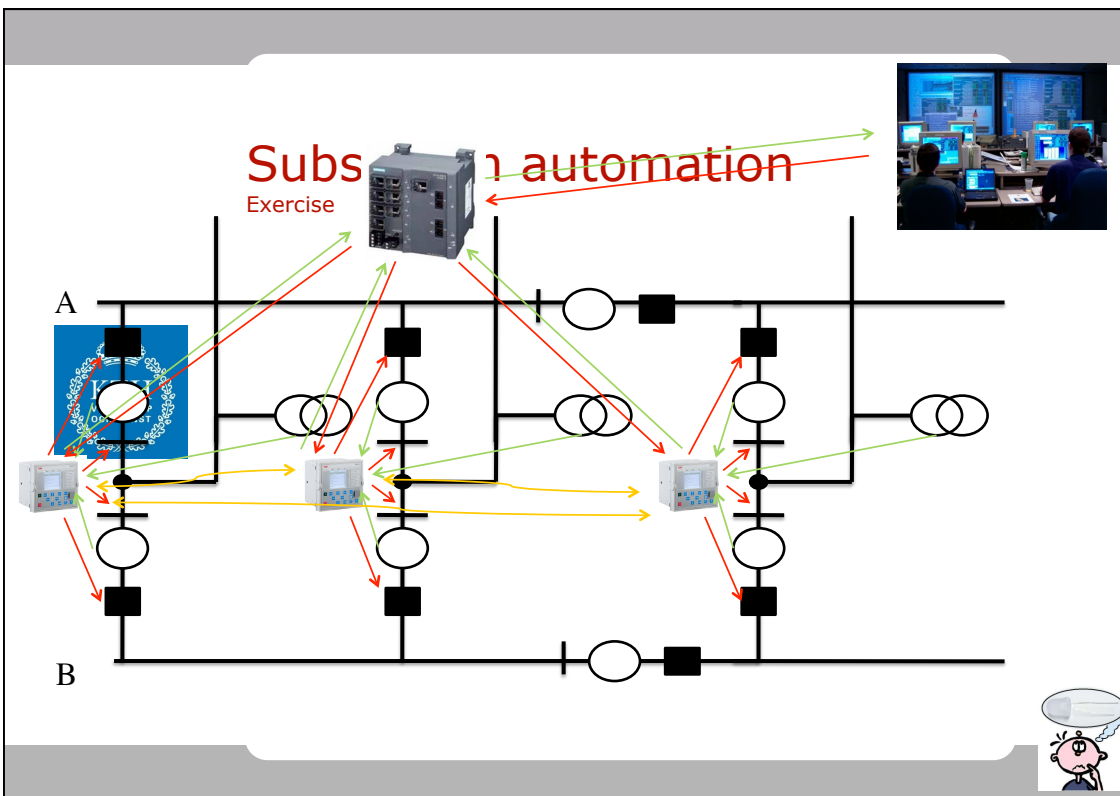
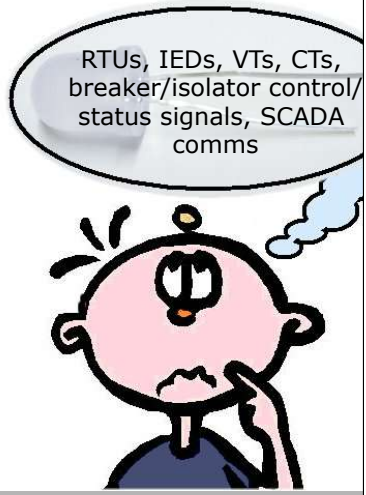
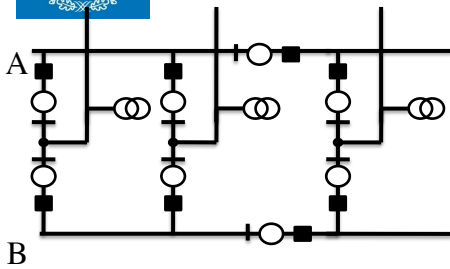
## SAS Discussion

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## Substation automation

- Given a double breaker station
  - Choose an interesting function to implement eg. interlocking
  - What kind of automation equipment
  - What would need to be communi





End of Part 5a