

Distributed Systems

ID2201



clocks

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What is time?

- No absolute time:
 - but for most practical purposes it is
- Assuming absolute time:
 - how can we tell the time
- If we're not synchronized what can we do:
 - causal effects give us logical time that order some events
 - does our distributed system give us a consistent view of logical time

Why?

- Give me an example where it is important to know the time.



Synchronization problems



- Who has the correct time?
 - earths rotation - UT1
 - one “atomic” clock - UTC
- Even if wee all agree, how do we keep nodes synchronized?
 - it takes time to send a signal
 - in between signals nodes will drift
 - how often can we send signals

Synchronization



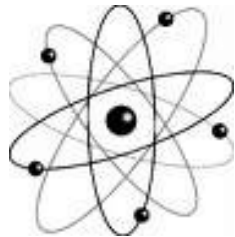
- External synchronization (accuracy)
 - each node in our network is synchronized with an external (global) source within a bound D
- Internal synchronization (precision)
 - every pair of nodes in our network are synchronized within a bound D

Drift and Monotonicity



- Drift is change in how well one clock can measure a time interval.
 - can drift change?
- Monotonicity is the property that time always moves forward.
 - can this be hard to guarantee?
- Correctness often means monotonicity and low drift.
- A correct clock might not be synchronized

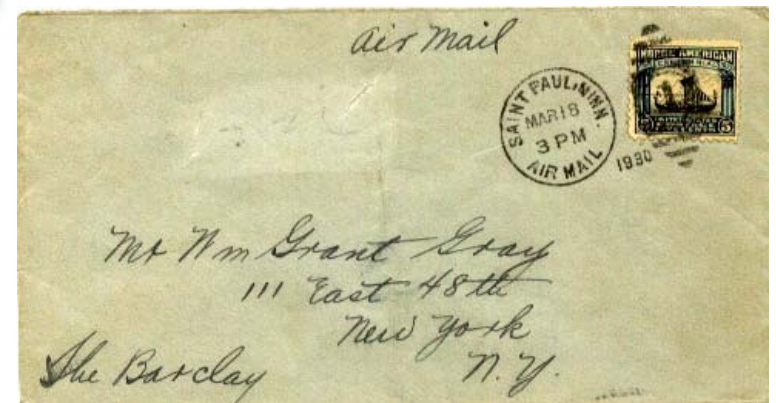
How to synchronize



~300 ns

033-415783

~100 ms



Asynchronous networks



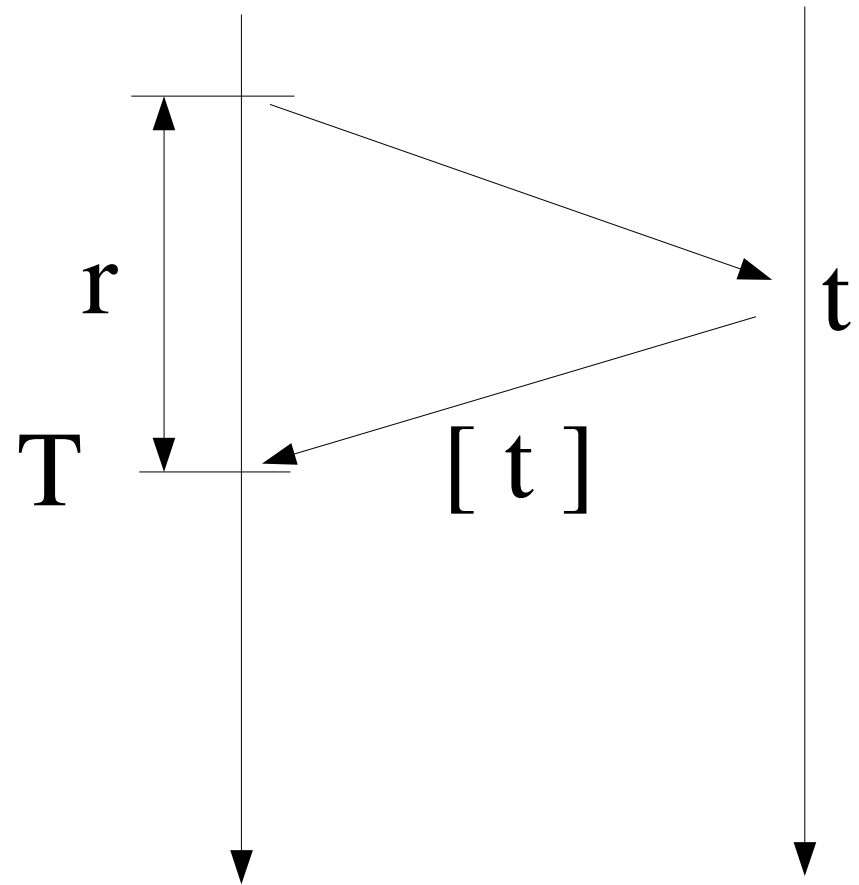
- One server is connected to external source and used to synchronize other nodes in the network.
- Problem is of course that round-trip times are unknown and that they vary.
- A minimum propagation time can be known.
- How do we synchronize our nodes?

Christian's algorithm



$$T = t + r/2$$

$$\text{diff} = r/2$$

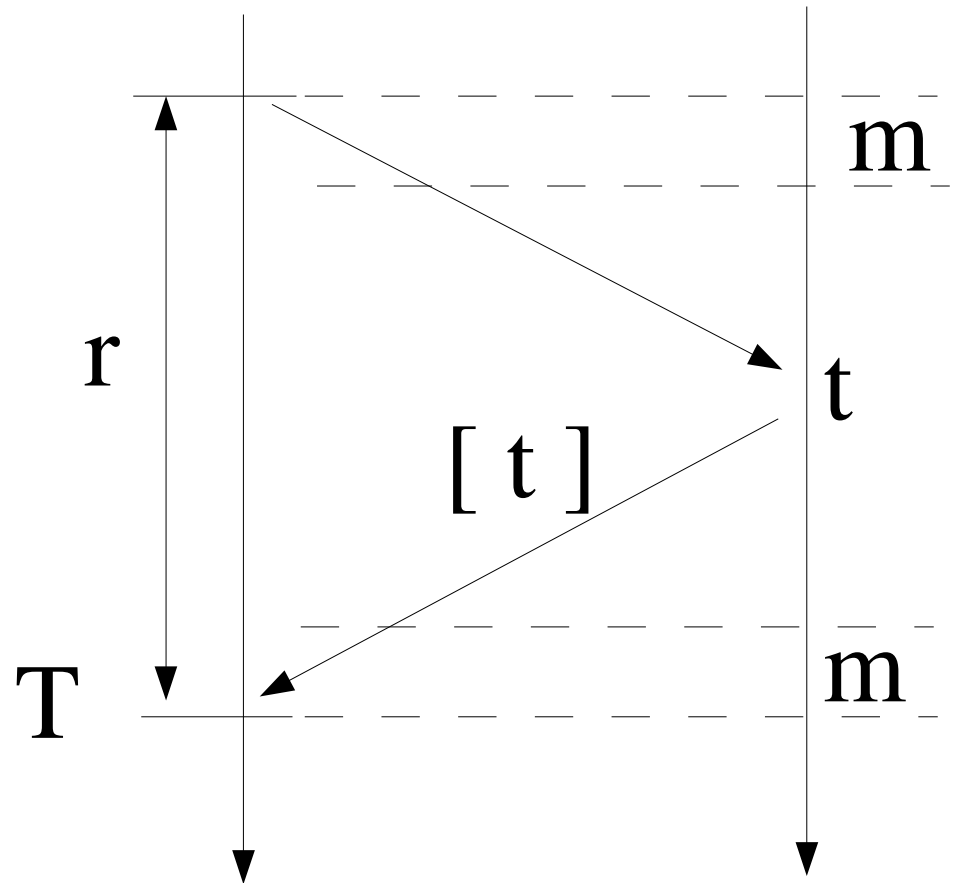


Christian's algorithm



$$T = t + r/2$$

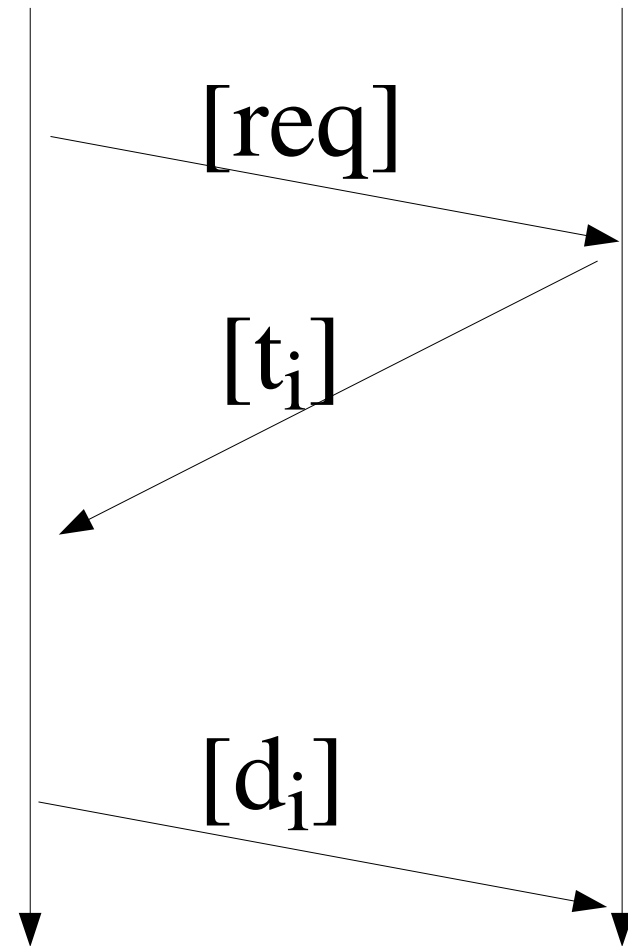
$$\text{diff} = r/2 - m$$





Berkeley algorithm

- Used to synchronize a network of nodes.
- Send requests to all nodes.
- Collect t_i and calculate an “average” time T .
- Send out individual deltas to each node.



NTP – network time protocol

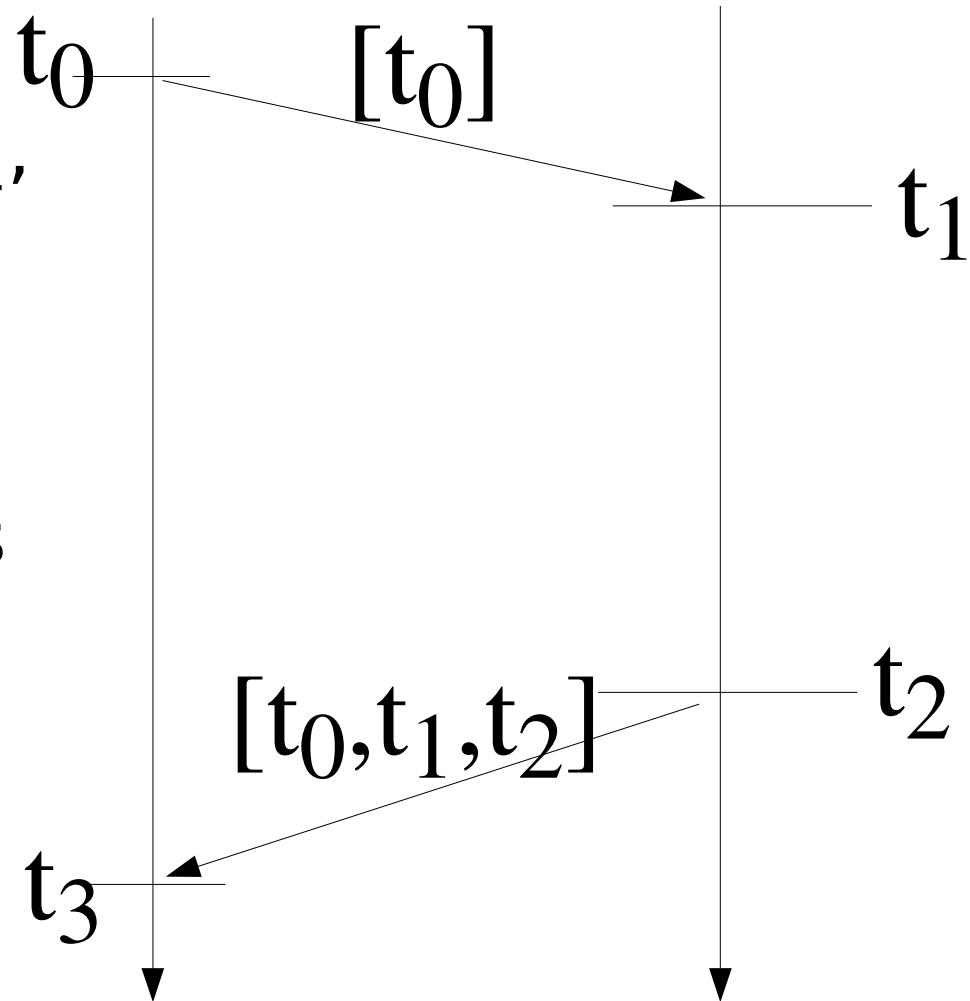


- An architecture targeting reliability and wide area networks.
- A hierarchy of servers: *stratum-1* connected to external sources.
- Fault tolerant: servers can be degraded to lower stratum if external source is lost, client can connect to secondary servers.
- Several synchronization protocols: LAN multicast, request and, synchronous.



NTP

- Client collects: t_0 , t_1 , t_2 and t_3 .
- The two messages are independent.
- Similar to Cristian's but with better estimate of delay.





Summary

- Clocks give us a estimate on real time.
- Clocks can be synchronized internally and/or to an external source.
- Synchronization limited by network jitter and clock drift.
- Synchronize to UTC
 - NTP connected over Internet: a few 10 ms
 - local GPS clocks connected to LAN: < 1 ms
 - on board GPS clock: few μ s to ns