Interactive Theorem Proving Lecture 3: Tactics, Locally Nameless Representation

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23 May 2024



Tactics in Coq

• Il y a plusieurs façons de plumer un canard

"There are many ways to pluck a duck"

Theorem P_if_P: forall P, P -> P. Proof. intros P HP. apply HP. (* Any of the following tactics will work exact HP. assumption. trivial. auto. eauto. intuition. *) Qed.





Goals and Subgoals

- In general a tactic is applied to a goal and either
 - Produces zero or more subgoals
 - Fails
- Some tactics never fail, e.g., simpl, auto, idtac...
- Some tactics fail if more than zero subgoals are produced, e.g. reflexivity
- Some tactics fail if an identical subgoal is produced, e.g. rewrite
- One tactic always fails, namely fail
 - Useful when writing tactics of your own





Focusing with Bullets

• When there are one or more subgoals, you can *focus* the proof with bullets

```
Theorem n_plus_Z:
  forall n,
    n + 0 = n.
Proof.
  intros n.
  induction n.
  (* Base case *)
    reflexivity.
  (* Inductive case *)
    simpl. rewrite IHn.
    reflexivity.
Qed.
```

Theorem n_plus_Z:
 forall n,
 n + 0 = n.
Proof.
 intros n.
 induction n.
 - (* Base case *)
 reflexivity.
 - (* Inductive case *)
 simpl. rewrite IHn.
 reflexivity.
Ged.

Subgoals on the same level must begin with the same kind of bullet



• Available bullets are -, +, *, --, ++, **, etc.

Focusing with Braces

• You can focus on a single goal with braces

```
Theorem n_plus_Z:
  forall n,
    n + 0 = n.
Proof.
  intros n.
  induction n.
  { (* Base case *)
    reflexivity.
  (* Inductive case *)
    simpl. rewrite IHn.
    reflexivity.
Qed.
```

```
Theorem n_plus_Z:
  forall n,
    n + 0 = n.
Proof.
  intros n.
  induction n.
  2: { (* Inductive case *)
    simpl. rewrite IHn.
    reflexivity.
  (* Base case *)
  reflexivity.
Qed.
```





Advice Regarding Focus

- Use bullets whenever you have more than one goal
- Use braces when you are side-stepping the "main story" of the proof

```
Theorem wf_expr_eval:
 forall n,
   wf_expr (length env) e ->
    exists n, eval expr env e = Some n.
Proof.
  (* ... *)
 - (* Case Var *)
    assert (Hex: exists n, nth_error env x = Some n).
    { destruct (nth_error env x).
      - exists n. reflexivity.
      - exfalso. apply H. reflexivity.
     *)
Qed.
```

"Here, we know that x has some value n (which we can show by case analysis on...)"





Running Example: An SSA Language

 $e ::= n | r_i | e + e | e^*e | isZero e? e : e$ $p ::= e; p | e \frac{\text{Register numbering}}{\text{is implicit}}$

 $env : \mathbb{N} \hookrightarrow \mathbb{N}$ $eval_expr : env \to e \hookrightarrow \mathbb{N}$ $eval_program : p \hookrightarrow \mathbb{N}$

Well-formedness:

 $\vdash p \iff p$ only mentions assigned variables

Main theorem: $\vdash p \implies \exists n . eval_program \ p = n$



Naming Things



Leon Bambrick @secretGeek

There are 2 hard problems in computer science: cache invalidation, naming things, and off-by-1 errors. Översätt inlägget 3:20 em · 1 jan. 2010

- Naming things is a hassle, but relying on generated names is worse
 - Adding a hypothesis to your proof can offset your H0, H1...
 - Updating your Coq version can change the numbering scheme(!)





How to Name Things

- Most tactics that introduce new terms and hypothesis support naming
 - destruct n as [| n']
 - induction l as [| x xs]
 - assert (Hlen: length l < 10)
- The way you declare data types matters

```
Inductive expr :=
| ENat : nat -> expr
| EVar : var -> expr
| EAdd : expr -> expr -> expr.
```

```
Inductive expr :=
| ENat : (n : nat)
| EVar : (x : var)
| EAdd : (e1 e2 : expr).
```

Running destruct will give the names n, v and e/e0

Running destruct will give the names n, x and e1/e2



How to Avoid Naming Things

• Sometimes you introduce something just to immediately forget it

```
destruct IHHwf as [n Heq].
rewrite Heq. (* Heq is no longer used *)
```

• Wherever an introduction pattern is used, you can immediately rewrite!

```
destruct IHHwf as [n ->].
(* Implicitly does rewrite -> Heq. clear Heq. *)
```

- With enough automation, you can find hypothesis automatically
 - A heavy alternative is match goal with (see later slides)





Tacticals

- Tacticals are tactics taking other tactics as arguments
 - tactic1; tactic2 run tactic2 on all subgoals generated by tactic1
 - tactic1 || tactic2 run tactic1, and if it fails run tactic2
 - try tactic run tactic but ignore if it fails
 - **repeat** tactic run tactic until it fails or generates an identical subgoal
 - **do** *n* tactic **run** tactic *n* **times**
 - progress tactic run tactic and require that it produces a new subgoal
 - **solve** tactic run tactic and fail if it generates more than zero subgoals
 - n: tactic run tactic on the nth goal in focus (1-indexed, can have ranges)
 - all: tactic run tactic on all goals in focus

Tacticals (cont.)

- Some tacticals work with lists of tactics
 - tactic1; [tac1 | ... | tacn] run taci on the ith subgoal of tactic1
 - **solve** [tac1 | ... | tacn] try solving with all listed tactics (in order)
 - **first** [tac1 | ... | tacn] run the first listed tactic that does not fail
- Two useful patterns:
 - Solve an assert without focusing: assert (H: ...); [apply foo; auto]].
 - Solving similar goals without accidentally touching other goals: induction e; try solve [assumption apply foo; auto

some other tactic].





Questions so far?



Automation

- The automation tactics search by applying hypotheses recursively
 - Is the current goal a hypotheses? If so, apply it and be done
 - Is the current goal the *conclusion* of a hypothesis? If so, apply it
 Hint Resolve my_pretty_lemma : hint_db.
 - Will also unfold (when told), intros and simpl when possible Hint Unfold my_pretty_fixpoint : hint_db.
- auto [with hint_db] proof search with simple apply
- eauto [with hint_db] proof search with simple eapply
- *intuition* [tactic] specialised for logic (can use tactic) NB: will update
 - Can destruct branching hypotheses: $P \lor Q \implies Q \lor P$ the goal!



Matching on the Goal

• Tactics can inspect the current proof state

• Can express "something containing e" with context [e]

```
match goal with
| _ : _ |- context[match ?e with | _ => _ end] => destruct e
end.
```







Extending Automation with Custom Tactics

• Matching on the goal is a great way of writing custom tactics

```
Ltac destruct_ex :=
  let n := fresh "n" in Generate fresh names to
  let Heq := fresh "Heq" in avoid collisions
  match goal with
  | H : exists n, _ = _ |- _ =>
     destruct H as [n Heq];
    try ((rewrite -> Heq in * || rewrite <- Heq in *);
        clear Heq)
end.</pre>
```

• Let *auto* (and friends) use your new tactic with some cost:

```
Hint Extern 1 => destruct_ex : hint_db.
```





Extending Automation with Custom Tactics

• A manual version together with an automatic

```
Ltac destruct_ex H :=
  let n := fresh "n" in
  let Heq := fresh "Heq" in
  match type of H with
  | exists n, _ = _ =>
     destruct H as [n Heq];
     try ((rewrite -> Heq in * || rewrite <- Heq in *);
        clear Heq)
  | _ => fail "Not an existential equality"
  end.
```

```
Ltac auto_destruct_ex :=
match goal with
    exists n, _ = _ |- _ => destruct_ex H
    _ |- _ => fail "No existential equalities in context"
end.
```



Using External Tactic Libraries

- The LibTactics chapter of Software Foundations has custom tactics
- These are from an external library called TLC by Arthur Charguéraud
 - Custom tactics that removes boilerplate
 - Alternative standard library (lists, sets, maps...)
 - Uses type classes heavily to reuse notations
 - NB: Assumes classical logic!
- One of my favourite tactics is introv:

```
Theorem transitivity:
   forall P Q R, (P -> Q) -> (Q -> R) -> P -> R.
Proof.
   introv PtoQ QtoR. (* same as intros P Q R PtoQ QtoR *)
   ...
```



Syntactic Conventions in TLC

- Most new tactics end with an "s" to distinguish them from originals
 - simpls like simpl, but better at unfolding
 - *substs* like *subst*, but handles circular equalities
 - inverts H like inversion H, but does substs and clear H
 - *applys* H like *apply* H, but better at handling quantifiers
- Automation makes it easy to say "and then do proof search"
 - tactic~ run tactic and then use "auto" on subgoals
 - tactic* run tactic and then use "eauto" on subgoals

induction~ n. simpls. rewrites~ IHn. Actually slightly more involved



Introduction Patterns in TLC

• There are introduction patterns that handle nesting better

```
Theorem foo:

forall A B (P Q : A -> B -> Prop),

(exists x y, P x y \land Q x y) ->

\sim(forall x y, \sim(P x y \land Q x y)).

Proof.

introv Hex.

destruct* Hex as (x & y & HP & HQ).

Qed.

Instead of

destruct Hex as [x [y [HP HQ]]]
```

Could also do *destructs** 4 Hex



Forward Reasoning in TLC

- Forward reasoning made simpler through two tactics
 - lets H: my_lemma arg1 ... argn instantiate my_lemma as H
 - *forwards* H: my_lemma [arg1 ... argn] like lets, but introduce existentials
- Together with automation they get rid of a lot of boilerplate

```
Lemma wf_program'_eval:
    forall env p,
    wf_program' (dom env) p ->
     exists n, eval_program' env p = Some n.
Proof.
    introv Hwf.
    inductions Hwf; simpls*.
    forwards~ (n & ->): wf_expr_eval.
Qed.
```



Other Brands Exist

- TLC is one alternative to the Coq standard library and tactics
 - <u>https://www.chargueraud.org/softs/tlc</u>
- The Iris project includes std++
 - <u>https://gitlab.mpi-sws.org/iris/stdpp</u>
- The SSReflect proof language uses a completely different style
 - <u>https://inria.hal.science/inria-00407778/document</u>







Time for a break!



The Locally Nameless Representation

Representing Variables

- We typically represent variables by using their names
 - $\lambda f. \lambda x. f x \qquad \lambda fst. \lambda snd. fst \\ \lambda x. \lambda y. y \qquad \lambda fst. \lambda snd. snd$
- This is natural when using pen and paper, but brings formal issues:
 - Names do not mean anything, α -equivalence instead of syntactic equality
 - The same name can be bound multiple times (shadowing)

 $\lambda x \cdot \lambda y \cdot x (\lambda x \cdot x y) \\ x_1 \quad x_1 \quad x_2 \quad x_2$

The Barendregt Convention

- In informal proofs we usually assume that all variables are distinct or can be renamed to avoid problems
- This is after Henk Barendregt who (quite literally) wrote the book on the lambda calculus
 - Barendregt in turn attributes this to Thomas Ottman
- When working in proof assistants, we are not this lucky...

Capture-Avoiding Substitution

• When substituting names, $tm[x \mapsto u]$ we need to check for shadowing:

 $\begin{array}{ll} (x)[x \mapsto u] &= u \\ (y)[x \mapsto u] &= y, \text{ if } x \neq y \\ (\lambda x \cdot tm)[x \mapsto u] &= \lambda x \cdot tm \\ (\lambda y \cdot tm)[x \mapsto u] &= \lambda x \cdot (tm[x \mapsto u]), \text{ if } x \neq y \\ (tm_1 \ tm_2)[x \mapsto u] &= (tm_1[x \mapsto u]) \ (tm_2[x \mapsto u]) \end{array}$

• β -reduction can use substitution

 $(\lambda x.tm) v \to tm[x \mapsto v]$

Typing Environments

• A typing environment maps variables to types

$$\begin{array}{c} x: T \in \Gamma \\ \hline \Gamma \vdash x: T \end{array} \qquad \begin{array}{c} \Gamma, x: T_1 \vdash tm: T_2 \\ \hline \Gamma \vdash \lambda x. tm: T_1 \rightarrow T_2 \end{array}$$

• Assuming no duplicates, order in the environment doesn't matter

$$\Gamma_1, \Gamma_2 \vdash tm : T \implies \Gamma_2, \Gamma_1 \vdash tm : T$$

Nameless Representation

- An alternative representation comes from Nicolaas de Bruijn
- A variable is an *index*, the distance to its λ -binder

 $\lambda f. \lambda x. f x \qquad \lambda fst. \lambda snd. fst \\\lambda . \lambda . 1 0 \qquad \lambda . \lambda . 1$ $\lambda x. \lambda y. y \qquad \lambda fst. \lambda snd. snd \\\lambda . \lambda . 0 \qquad \lambda . \lambda . 0$

• Equivalent terms are syntactically equivalent! Shadowing not an issue:

$$\lambda x . \lambda y . x (\lambda x . x y)$$
$$\lambda . \lambda . 1 (\lambda . 0 1)$$

Substitution and Shifting

• When manipulating terms, we need to handle indices with care

 $\begin{array}{ll} (n)[n \mapsto u] &= u \\ (m)[n \mapsto u] &= m, \text{ if } m \neq n \\ (\lambda \cdot tm)[n \mapsto u] &= \lambda x \cdot (tm[n+1 \mapsto \uparrow_0^1 u]) \\ (tm_1 \ tm_2)[n \mapsto u] = (tm_1[n \mapsto u]) \ (tm_2[n \mapsto u]) \end{array}$

 $\begin{array}{l} \uparrow_{c}^{i}(n) &= n+i, \text{ if } n \geq c \\ \uparrow_{c}^{i}(n) &= n, \text{ if } n < c \\ \uparrow_{c}^{i}(n)(\lambda \cdot tm) &= \lambda x \cdot (\uparrow_{c+1}^{i} tm) \\ \uparrow_{c}^{i}(n)(tm_{1} tm_{2}) = (\uparrow_{c}^{i} tm_{1}) (\uparrow_{c}^{i} tm_{2}) \end{array}$

• β -reduction becomes a lot trickier!

 $(\lambda . tm) v \rightarrow \uparrow_0^{-1} (tm[0 \mapsto \uparrow_0^1 v])$

Typing Environments

• A typing environment is a list of types

 $\begin{array}{c} \Gamma[n] = T \\ \Gamma \vdash n : T \end{array} \qquad \begin{array}{c} T_1, \Gamma \vdash tm : T_2 \\ \Gamma \vdash \lambda . tm : T_1 \to T_2 \end{array} \end{array}$

- The order in the environment very much matters!
- Weakening needs to update all indices

 $\Gamma_1 \vdash tm : T \implies \Gamma_2, \Gamma_1 \vdash \uparrow_0^{|\Gamma_2|} tm : T$

• Our jobs as theoreticians gets harder!

Middle Ground: Locally Nameless

- Good introduction in paper by Arthur Charguéraud (but concept older)
- Idea:
 - Use *nameless* representation for *bound* variables
 - Use *named* representation for *free* variables
- As soon as we "look under a λ ", introduce a fresh variable

 $\{\} \vdash \lambda . \lambda . 1 0$ $\{f\} \vdash \lambda . f 0$ $\{f, x\} \vdash f x$

Opening and Substitution

• Substitution of free variables no longer needs to care about shadowing!

 $\begin{array}{ll} (x)[x \mapsto u] &= u \\ (y)[x \mapsto u] &= y, \text{ if } x \neq y \\ (n)[x \mapsto u] &= n \\ (\lambda \cdot tm)[x \mapsto u] &= \lambda \cdot (tm[x \mapsto u]) \\ (tm_1 \ tm_2)[x \mapsto u] = (tm_1[x \mapsto u]) \ (tm_2[x \mapsto u]) \end{array}$

• We substitute bound variables by *opening* terms, $tm^u = tm\{0 \mapsto u\}$

$(n)\{n\mapsto u\}$	= u
$(m)\{n\mapsto u\}$	$= m$, if $m \neq n$
$(x)\{n \mapsto u\}$	= x
$(\lambda . tm)\{n \mapsto u\}$	$=\lambda x.(tm\{n+1\mapsto u\})$
$(tm_1 \ tm_2)\{n \mapsto u\}$	$= (tm_1\{n \mapsto u\}) \ (tm_2\{n \mapsto u\})$

Opening and Substitution

- Substitution of free variables no longer needs to care about shadowing!
- We substitute bound variables by *opening* terms, $tm^u = tm\{0 \mapsto u\}$

$(x)[x \mapsto u] \qquad = u$	$(n)\{n\mapsto u\}$ =	= u
$(y)[x \mapsto u] = y, \text{ if } x \neq y$	$(m)\{n\mapsto u\}$ =	$= m$, if $m \neq n$
$(n)[x \mapsto u] = n$	$(x)\{n\mapsto u\} \qquad = \qquad$	= x
$(\lambda . tm)[x \mapsto u] = \lambda . (tm[x \mapsto u])$	$(\lambda . tm)\{n \mapsto u\} =$	$=\lambda x.(tm\{n+1\mapsto u\})$
$(tm_1 \ tm_2)[x \mapsto u] = (tm_1[x \mapsto u]) \ (tm_2[x \mapsto u])$	$(tm_1 \ tm_2)\{n \mapsto u\}=$	$=(tm_1\{n\mapsto u\})\ (tm_2\{n\mapsto u\})$

- β -reduction uses opening, but we can prove equivalence with substitution $(\lambda \cdot tm) \ v \to tm^{v}$
 - $x \notin fv(tm) \implies tm^u = tm^x[x \mapsto u]$

Typing Environments

• Typing environments map variables to types, but we pick the names!

 $\begin{array}{ccc} x:T \in \Gamma & \forall x \notin L & \Gamma, x:T_1 \vdash tm^x:T_2 \\ \hline \Gamma \vdash x:T & \Gamma \vdash \lambda . tm:T_1 \rightarrow T_2 \end{array}$

- $\forall x \notin L$ is *cofinite quantification*: we show the rule for any x not in some finite set L
- Since we can always pick fresh names, order in the environment doesn't matter $\Gamma_1, \Gamma_2 \vdash tm : T \implies \Gamma_2, \Gamma_1 \vdash tm : T$

• Weakening is straightforward, as before

 $\mathbf{dom}(\Gamma_1) \cap \mathbf{dom}(\Gamma_2) = \emptyset \implies$ $\Gamma_1 \vdash tm : T \implies \Gamma_2, \Gamma_1 \vdash tm : T$

Locally Closed Terms

- Since we open terms by need, indices are never "out of bounds"
 - Terms like λ .1 are meaningless
- We can formalise terms being locally closed as the relation lc

$$\frac{lc \ tm_1 \ lc \ tm_2}{lc \ x} \qquad \frac{lc \ tm_1 \ lc \ tm_2}{lc(tm_1 \ tm_2)} \qquad \frac{\forall x \notin L \ lc \ tm^x}{lc(\lambda \ . tm)}$$

• With locally closed terms, we get a bunch of useful facts, for example $lc \ tm \implies tm^{u} = tm$ $lc \ u \land x \neq y \implies (tm^{y})[x \mapsto u] = (tm[x \mapsto u])^{y}$ $lc \ u \implies (tm^{v})[x \mapsto u] = (tm[x \mapsto u])^{v[x \mapsto u]}$

Questions before we go back to Coq?

Conclusions

- Automation is what makes large proof developments feasible
 - Avoids spending time on trivial subgoals
 - Makes your development more robust to change
- Having a good standard library makes a big difference
 - Having to prove mundane things e.g. lists is surprisingly common
- Dealing with name binding and substitution is boring and technical
 - Locally nameless is **one** way to make definitions simpler
 - Having good library support helps a lot too!

