## IE1206 Embedded Electronics



## Easy to generate a sinusoidal voltage

Our entire power grid works with sinusoidal voltage.

When the loop rotates with constant speed in a magnetic field a sine wave is generated.

So much easier, it can not be


The sine wave - what do you remember?


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## (11.1) Phase $\varphi$

If a sine curve does not begin with 0 the function expression has a phase angle $\varphi \cdot{ }_{y(t)=\hat{Y} \sin (\omega t+\varphi)}$
Specify this function mathematically:


$$
\begin{gathered}
u(t)=6 \cdot \sin (2 \pi \cdot 1000 \cdot t+\varphi) \\
u(0)=3=6 \cdot \sin (\varphi) \Rightarrow \varphi=\arcsin \left(\frac{3}{6}\right)=0,52 \mathrm{rad} \quad\left(=30^{\circ}\right) \\
u(t)=6 \cdot \sin (6283 \cdot t+0,52)
\end{gathered}
$$

## Apples and pears?

In circuit analyses it is common (eg. in textuvons) io expresses the angle of the sine function mixed in radians $\omega \cdot t[\mathrm{rad}]$ and in degrees $\varphi\left[^{\circ}\right]$.

This is obviously improper, but practical (!). The user must "convert" phase angle to radians to calculate the sine function value for any given time $t$.
(You have now been warned ...)

$$
u(t)=6 \cdot \sin \left(6283 \cdot t+30^{\circ}\right)
$$

$$
\begin{aligned}
& \text { Conversion: } \\
& x\left[^{\circ}\right]=x[\mathrm{rad}] \cdot 57,3 \\
& x[\mathrm{rad}]=x\left[^{\circ}\right] \cdot 0,017
\end{aligned}
$$

## Mean and effective value

All pure AC voltages, has the mean value 0.

- More interesting is the effective value - root mean square, rms.



## (11.2) Example. RMS.

The rms value is what is normally used for an alternating voltage $\boldsymbol{U} .1,63 \mathrm{~V}$ effective value gives the same power in a resistor as a $1,63 \mathrm{~V}$ pure DC voltage would do.


$$
U=\sqrt{\frac{\int_{0}^{T} u(t)^{2} \mathrm{~d} t}{T}}=\sqrt{\frac{\left(2^{2}+(-2)^{2}+0\right) \cdot 5 \cdot 10^{-3}}{15 \cdot 10^{-3}}}=\sqrt{\frac{8 \cdot 5 \cdot 10^{-3}}{15 \cdot 10^{-3}}}=1,63 \mathrm{~V}
$$

## Sine wave effective value

## Ex. 11.3

$\sin ^{2}$ has the mean value $1 / 2$

Therefore:


- Effective value is often called RMS ( Root Mean Square ).


## Addition of sinusoidal quantities

$$
y_{2}=\hat{A}_{2} \sin \left(\omega t+\varphi_{2}\right)
$$

$$
\begin{gathered}
+ \\
y_{1}+y_{2}=?
\end{gathered}
$$

$$
\sim
$$

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## Addition of sinusoidal quantities

When we shall apply the circuit laws on AC circuits, we must add the sines. The sum of two sinusoidal quantities of the same frequency is always a new sine of this frequency, but with a new amplitude and a new phase angle.
( Ooops! The result of the rather laborious calculations are shown below).

$$
\begin{aligned}
& y_{1}(t)=\hat{\mathrm{A}}_{1} \cdot \sin \left(\omega t+\varphi_{1}\right) \quad y_{2}(t)=\hat{\mathrm{A}}_{2} \cdot \sin \left(\omega t+\varphi_{2}\right) \quad y(t)=y_{1}(t)+y_{2}(t)= \\
& =\sqrt{\hat{\mathrm{A}}_{1}^{2}+\hat{\mathrm{A}}_{2}^{2}+2 \hat{\mathrm{~A}}_{1} \hat{\mathrm{~A}}_{2} \cos \left(\varphi_{1}-\varphi_{2}\right)} \cdot \sin \left(\omega t+\arctan \frac{\hat{\mathrm{A}}_{1} \sin \left(\varphi_{1}\right)+\hat{\mathrm{A}}_{2} \sin \left(\varphi_{2}\right)}{\hat{\mathrm{A}}_{1} \cos \left(\varphi_{1}\right)+\hat{\mathrm{A}}_{2} \cos \left(\varphi_{2}\right)}\right)
\end{aligned}
$$

## Sine wave as a pointer

A sinusoidal voltage or current,

$$
y(t)=\hat{Y} \cdot \sin (\omega \cdot t)
$$

can be represented by a pointer that rotates (counterclockwise) with the angular velocity $\omega[\mathrm{rad} / \mathrm{sec}]$.

Wikipedia Phasors

## Simpler with vectors



If you ignore the "revolution" and adds the pointers with vector addition, as they stand at the time $t=0$, it then becomes a whole lot easier!

## 4) Wikipedia Phasors

http://en.wikipedia.org/wiki/Phaso

## Pointer with complex numbers

A AC voltage 10 V that has the phase $30^{\circ}$ is usually written:

$$
10 \angle 30^{\circ} \quad \text { (Phasor ) }
$$

Once the vector additions require more than the most common geometrical formulas, it is instead preferable to represent pointers
 with complex numbers.

$$
10 \angle 30^{\circ} \Leftrightarrow 10 \cdot \mathrm{e}^{\mathrm{j} 30^{\circ}} \Leftrightarrow 10 \cdot \cos 30^{\circ}+10 \cdot \mathrm{j} \cdot \sin 30^{\circ}
$$

In electricity one uses $\mathbf{j}$ as imaginary unit, as $\mathbf{i}$ is already in use for current.

## Phasor

Sinusoidal alternating quantities can be represented as pointers, phasors.
"amount" L"phase"
A pointer (phasor) can either be viewed as a vector expressed in polar coordinates, or as a complex number.

It is important to be able to describe alternating current phenomena without necessarily having to require that the audience has a knowledge of complex numbers - hence the vector method.

The complex numbers and j $\omega$-method are powerful tools that facilitate the processing of AC problems. They can be generalized to the Fourier transform and Laplace transform, so the electro engineer's use of complex numbers is extensive.

## peak/effective value - phasor



The phasor lengths corresponds to sine peak values, but since the effective value only is the peak value scaled by $1 / \sqrt{ } 2$ so it does not matter if you count with peak values or effective values - as long as you are consistent!

## The inductor and capacitor counteracts changes

The inductor and capacitor counteracts changes, such as when connecting or disconnecting a source to a circuit.

What if the source then is sinusoidal AC - which is then changing continuously?

?

## Alternating current through resistor

A sinusoidal current $i_{\mathrm{R}}(t)$ through a resistor $R$ provides a proportional sinusoidal voltage drop $u_{\mathrm{R}}(t)$ according to Ohm's law. The current and voltage are in phase. No energy is stored in the resistor.

Phasors $U_{\mathrm{R}}$ and $I_{\mathrm{R}}$ become parallel to each other.

$$
U_{R}=R I_{R}
$$

$$
\begin{aligned}
& i_{\mathrm{R}}(t)=\hat{I}_{\mathrm{R}} \cdot \sin (\omega t) \quad u_{\mathrm{R}}(t)=i_{\mathrm{R}}(t) \cdot R \quad \Rightarrow \quad u_{\mathrm{R}}(t)=R \cdot \hat{I}_{\mathrm{R}} \cdot \sin (\omega t) \\
& U_{\mathrm{R}}=R \cdot I_{\mathrm{R}} \quad \text { - Vector phasor } \\
& \underline{U}_{\mathrm{R}}=R \cdot \underline{I}_{\mathrm{R}} \quad \text { - Complex phasor }
\end{aligned}
$$

The phasor may be a peak pointer or effective value pointer as long as you do not mix different types.

## Alternating current through inductor

A sinusoidal current $i_{\mathrm{L}}(t)$ through an inductor $\bigwedge U_{\mathrm{L}}=2 \pi f L I_{\mathrm{L}}$ provides, due to self-induction, a votage drop $u_{\mathrm{L}}(t)$ which is $90^{\circ}$ before the current. Energy stored in the magnetic field is used to provide this voltage.


The phasor $U_{\mathrm{L}}$ will be $\omega L \cdot I_{\mathrm{L}}$ and it is $90^{\circ}$ before $I_{\mathrm{L}}$. The entity $\omega L$ is the "amount" of the inductor's AC resistance, reactance $X_{\mathrm{L}}[\Omega]$.
$i_{\mathrm{L}}(t)=\hat{I}_{\mathrm{L}} \cdot \sin (\omega t) \quad u_{\mathrm{L}}(t)=L \frac{\mathrm{~d} i_{\mathrm{L}}(t)}{\mathrm{d} t} \Rightarrow u_{\mathrm{L}}(t)=\omega L \cdot \hat{I}_{L} \cdot \cos (\omega t)=\omega L \cdot \hat{I}_{L} \cdot \sin \left(\omega t+\frac{\pi}{2}\right)$
$U_{L}=\omega L \cdot I_{L} \quad$ - Vector phasor
When using complex pointers one multiplies $\omega L$ with " $j$ ", this rotates the voltage pointer $+90^{\circ}$ (in complex plane). The method automatically keeps track of the phase angles!

$$
\underline{U}_{\mathrm{L}}=\mathrm{j} \omega L \cdot \underline{I}_{\mathrm{L}}=\mathrm{j} X_{\mathrm{L}} \cdot \underline{I}_{\mathrm{L}}
$$

- Complex phasor


## Alternating current through capacitor

A sinusoidal current $i_{\mathrm{C}}(t)$ throug a capacitor will charge it with the "voltage drop" $u_{\mathrm{C}}(t)$ that lags $90^{\circ}$ behind the current. Energy is storered in the electric $u_{c} \vee u_{c}=\frac{1}{2 \pi f C} I_{c}$
field.

Phasor $U_{\mathrm{C}}$ is $I_{\mathrm{C}} /(\omega C)$ and it lags $90^{\circ}$ after $I_{\mathrm{C}}$. The entity $1 /(\omega C)$ is the "amount" of the

$$
U_{\mathrm{C}}=\frac{1}{\omega C} \cdot I_{\mathrm{C}}
$$ capacitor's AC resistance, reactance $X_{\mathrm{C}}[\Omega]$.

- Vector phasor

$$
\begin{aligned}
& U=\frac{Q}{C} \Rightarrow \frac{\mathrm{~d} u_{\mathrm{C}}(t)}{\mathrm{d} t}=\frac{1}{C} \cdot \frac{\mathrm{~d} q}{\mathrm{~d} t}=\frac{1}{C} \cdot i_{\mathrm{C}}(t) \Rightarrow u_{\mathrm{C}}(t)=\frac{1}{C} \cdot \int i_{\mathrm{C}}(t) \mathrm{d} t \\
& i_{\mathrm{C}}(t)=\hat{I}_{\mathrm{C}} \cdot \sin (\omega t) \Rightarrow u_{\mathrm{C}}(t)=-\frac{1}{\omega C} \cdot \hat{I}_{\mathrm{C}} \cdot \cos (\omega t)=\frac{1}{\omega C} \cdot \hat{I}_{\mathrm{C}} \cdot \sin \left(\omega t-\frac{\pi}{2}\right)
\end{aligned}
$$

## Complex phasor and the sign of reactance

If you use complex phasor you get the $-90^{\circ}$ phase by dividing ( $1 / \omega C$ ) with " j ".


The method with complex pointer automatically keeps track of the phase angles if we consider the capacitor reactance $\boldsymbol{X}_{\mathbf{C}}$ as negative, and hence the inductor reactance $\boldsymbol{X}_{\mathrm{L}}$ as positive.

$$
\underline{U}_{C}=\frac{1}{\mathrm{i} \omega C} \cdot \underline{I}_{C}=\mathrm{j} \frac{-1}{\omega C} \cdot \underline{I}_{C} \quad \Rightarrow \begin{array}{|c}
X_{C}=\frac{1}{\omega C}
\end{array} \text { •Complex phasor }
$$

## L+C in series


$M$


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## Reactance frequency dependency




$$
\begin{gathered}
\left|X_{L}\right|=\omega \cdot L \quad\left|X_{C}\right|=\frac{1}{\omega \cdot C} \\
\omega=2 \pi f
\end{gathered}
$$

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## LOG - LOG plot

$$
\log \left(\left|X_{L}\right|\right)-\text { scale }[\Omega]
$$


$\log (f)-$ scale $[\mathrm{Hz}]$
$\log \left(\left|X_{C}\right|\right)-$ scale $[\Omega]$

$\log (f)-$ scale $[\mathrm{Hz}]$

Often electronics engineers use log-log scale. The inductor and capacitor reactances will then both be "linear" relationship in such charts.

## $R L C$



In general, our circuits are a mixture of different $R L$ and $C$.
The phase between $I$ and $U$ is then not $\pm 90^{\circ}$ but can have any intermediate value. Positive phase means that the inductances dominates over capacitances, we have inductive character IND. Negative phase means that the capacitance dominates over the inductances, we have capacitive character CAP.
The ratio between the voltage $U$ and current $I$, the AC resistance, is called impedace $Z[\Omega]$. We then have OHM's AC law:

$$
Z=\frac{U}{I}
$$

## Phasor diagrams



In order to calculate the AC resistance, the impedance, $Z$, of a composite circuit one must add currents and voltages phasors to obtain the total current $I$ and the total voltage $U$.


$$
Z=\frac{U}{I}
$$

The phasor diagram is our "blind stick" in to the AC World!

## Ex. Phasor diagram (11.5)

Elementary diagrams for $R L$ and $C$


At a certain frequency $f$ the capacitor has the reactance $\left|X_{\mathrm{C}}\right|$ and the resistor $R$ has the same amount (absolute value), $\mathrm{R}[\Omega]$.

Use the elementary diagrams for $R$ and $C$ as building blocks to draw the whole circuit phasor diagram (for this actual frequency $f$ ).


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## Example. Phasor diagram.



1) $U_{2}$ reference phase ( = horizontal )

2) $\bar{I}_{\mathrm{R}} \| \bar{U}_{2} \xrightarrow{U_{\mathrm{B}}}{ }^{I_{\mathrm{g}}}$
3) $\bar{I}_{\mathrm{C}} \perp \bar{U}_{2} \quad I_{\mathrm{C}}=I_{\mathrm{R}}=\frac{U_{2}}{R} \quad \stackrel{U_{\mathrm{c}}}{ } \xrightarrow{I_{c}}$
4) $\bar{I}=\bar{I}_{\mathrm{R}}+\bar{I}_{\mathrm{C}} \quad I=\sqrt{2} \cdot I_{\mathrm{C}}$
5) $\overline{U_{1} \perp \bar{I}} U_{c} \sqrt{1}$

$$
U_{1}=I \cdot R=I_{\mathrm{C}} \cdot \sqrt{2} \cdot R \Rightarrow U_{1}=\sqrt{2} \cdot U_{2}
$$

6) $\bar{U}=\bar{U}_{1}+\bar{U}_{2}$



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## Impedance $Z$

The circuit AC resistance, impedance $Z$, one get as the ratic $\stackrel{U, t}{\sim}$ between the length of $U$ and $I$ phasors. The impedance phase $\varphi$
 is the angle between $U$ and $I$ phasors.

The current is before the voltage in phase, so the circuit has a capacitive character, CAP.
( Something else had hardly been to wait since there are no coils in
 the circuit)

## Complex phasors, j $\omega$-method

Complex phasors. OHM's law for $R L$ and $C$.

$$
\begin{array}{ll}
\underline{U}_{\mathrm{R}}=\underline{I}_{\mathrm{R}} \cdot R & \varphi=\arg (R)=0^{\circ} \\
\underline{U}_{\mathrm{L}}=\underline{I}_{\mathrm{L}} \cdot \mathrm{j} X_{\mathrm{L}}=\underline{I}_{\mathrm{L}} \cdot \mathrm{j} \omega L & \varphi=\arg (\mathrm{j} \omega L)=+90^{\circ} \\
\underline{U}_{\mathrm{C}}=\underline{I}_{\mathrm{C}} \cdot \mathrm{j} X_{\mathrm{C}}=\underline{I}_{\mathrm{C}} \cdot \frac{1}{\mathrm{j} \omega C} & \varphi=\arg \left(\frac{1}{\mathrm{j} \omega C}\right)=-\arg (\mathrm{j} \omega C)=-90^{\circ}
\end{array}
$$

Complex phasors. OHM's law for $Z$.

$$
\underline{U}=\underline{I} \cdot \underline{Z} \quad Z=\frac{U}{I} \quad \varphi=\arg (\underline{Z})=\arg \left(\frac{U}{\underline{I}}\right)=\arg (\underline{U})-\arg (\underline{I})
$$

$$
\begin{array}{lc}
\operatorname{Re}[\underline{U}]=\operatorname{Re}[\underline{I} \cdot \underline{Z}] & \arg (\underline{Z})=\arctan \left(\frac{\operatorname{Im}[\underline{Z}]}{\operatorname{Re}[\underline{Z}]}\right)=\arctan \left(\frac{X}{R}\right) \\
\operatorname{Im}[\underline{U}]=\operatorname{Im}[\underline{I} \cdot \underline{Z}] & \begin{array}{l}
\text { In fact, there will be four useful relationships! } \\
\bullet \text { Re, } \bullet \text { Im, } \bullet \text { Abs, } \bullet \text { Arg }
\end{array} \\
\end{array}
$$

## Ex. Complex phasors.



## Ex. Complex phasors.



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## Ex. Complex phasors.

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## Ex. Complex phasors. I



## Ex. Complex phasors. $U_{1}$



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## Ex. Complex phasors. $U_{1}$



$$
\begin{aligned}
& \underline{U}_{1}=\underline{I} \cdot \frac{1}{\mathrm{j} \omega C}=(0,4+1,2 \mathrm{j}) \cdot(-10 \mathrm{j})=12-4 \mathrm{j} \\
& U_{1}=|12-4 \mathrm{j}|=\sqrt{12^{2}+(-4)^{2}}=12,65
\end{aligned}
$$

## Ex. Complex phasors. $U_{2}$



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## Ex. Complex phasors. $U_{2}$



$$
\begin{aligned}
& \underline{U}_{2}=\underline{U} \cdot \frac{\underline{Z}_{\mathrm{R} / / \mathrm{C}}}{\frac{1}{\mathrm{j} \omega C}+\underline{Z}_{\mathrm{R} / / \mathrm{C}}}=20 \cdot \frac{5-5 \mathrm{j}}{-10 \mathrm{j}+(5-5 \mathrm{j})}=20 \cdot \frac{1-\mathrm{j}}{1-3 \mathrm{j}} \cdot \frac{(1+3 \mathrm{j})}{(1+3 \mathrm{j})}=8+4 \mathrm{j} \\
& U_{2}=|8+4 \mathrm{j}|=\sqrt{8^{2}+4^{2}}=8,94
\end{aligned}
$$

## Ex. Complex phasors. $I_{C}$



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## Ex. Complex phasors. $I_{C}$



$$
\begin{aligned}
& \underline{I}_{\mathrm{C}}=\frac{\frac{U_{2}}{\frac{1}{\mathrm{j} \omega C}}=\frac{8+4 \mathrm{j}}{-10 \mathrm{j}}=-0,4+0,8 \mathrm{j}}{} \\
& I_{\mathrm{C}}=|0,4+0,8 \mathrm{j}|=\sqrt{0,4^{2}+0,8^{2}}=0,89
\end{aligned}
$$

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## Ex. Complex phasors. $I_{\mathrm{R}}$



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## Ex. Complex phasors. $I_{\mathrm{R}}$



$$
\begin{aligned}
& \underline{I}_{\mathrm{R}}=\frac{\underline{U}_{2}}{R}=\frac{8+4 \mathrm{j}}{10}=0,8+0,4 \mathrm{j} \\
& I_{\mathrm{R}}=|0,8+0,4 \mathrm{j}|=\sqrt{0,8^{2}+0,4^{2}}=0,89
\end{aligned}
$$



## Vrida diagrammet ...

When we draw the phasor diagram it was natural to have $\boldsymbol{U}_{2}$ as reference phase (=horizontal), with the $\mathrm{j} \omega$ method $\boldsymbol{U}$ was the natural choice of reference phase (=real).

Because it is easy to rotate the chart, so, in practice, we have the freedom of choosing any entity as the reference.

$$
\arg \left(\underline{U}_{2}\right)=\arg (8+4 \mathrm{j})=\arctan \left(\frac{4}{8}\right)=26,7^{\circ}
$$

$\times\left(\cos \left(-26,7^{\circ}\right)+\mathrm{j} \cdot \sin \left(-26,7^{\circ}\right)\right) \quad$ Multiply the all complex numbers by this factor and rhe rotation will take effect!

## Summary

Sinusoidal alternating quantities can be represented as pointers, phasors,

$$
\text { "amount" } \angle \text { "phase". }
$$

A pointer (phasor) can either be seen as a vector expressed in polar coordinates, or as a complex number.

Calculations are usually best done with the complex method, while phasor diagrams are used to visualize and explain alternating current phenomena.

## Notation

$x$ Instant value
$\hat{X} \quad$ Top value
$\underline{X}$ Complex phasor
$X|\underline{X}|$ Absolute value, the amount

