



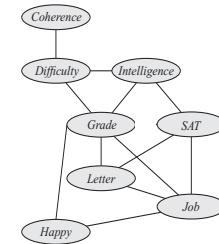
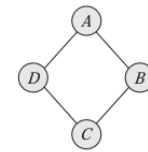
Royal Institute of Technology

STAT. METH. IN
CS - EXACT
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20

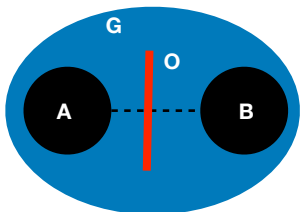
Lecture 8

UGM

- ★ UGMs - Undirected graphical models
- ★ What is the direction between 2 pixels, 2 proteins?
- ★ Probabilistic interpretation?
- ★ p factorizes over G - can be expressed as normalized product over factors associated with cliques
- ★ here categorical



SEPARATION AND CI OF UGM



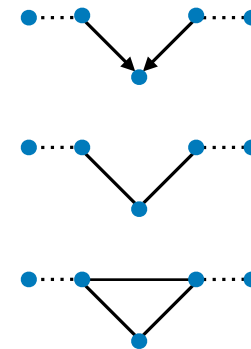
- ★ A is separated from B given O in G if there is no path between A and B in $G \setminus O$
- ★ In a graph G,



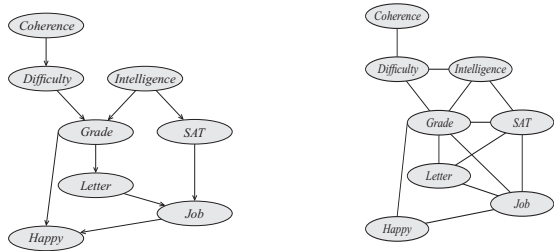
A is separated from B given O

DEF I-MAP

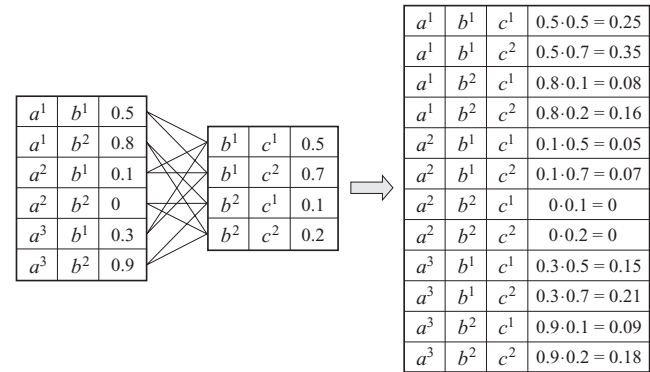
- G is an I-map for p if all independence relation in G hold for p, i.e., $I(G) \subseteq I(p)$
- Moralize add edge between any two parents
- We can moralize a DGM and get a UGM having no more independence relations
- Each family has a cliques in the moralized UGM



CONVERTING DGM TO UGM & SING JUNCTION TREE

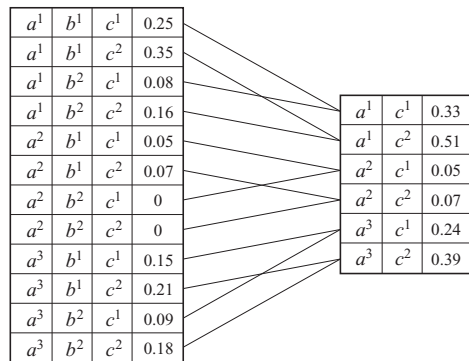


- Moralize and remove directions
- Families are cliques
- does not introduce new independencies!
- Cliques in bags of any Junction tree
- Use CPDs as factors
- We will work with marginals of bags

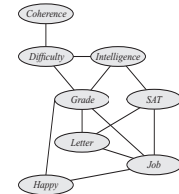


A FACTOR PRODUCT

SUMMING OUT - IN FACTOR



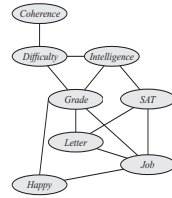
JOINT AS FACTOR PRODUCT



$$P(C, D, I, G, S, L, J, H) = P(C)P(D|C)P(I)P(G|I, D)P(S|I)P(L|G)P(J|L, S)P(H|G, J)$$

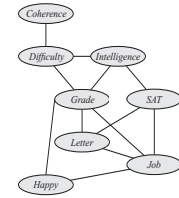
$$p(C, D, I, G, S, L, J, H) = \psi_C(C)\psi_D(D, C)\psi_I(I)\psi_G(G, I, D)\psi_S(S, I)\psi_L(L, G)\psi_J(J, L, S)\psi_H(H, G, J)$$

SUMMING OUT



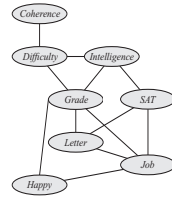
$$p(J) = \sum_L \sum_S \sum_G \sum_H \sum_I \sum_D \sum_C p(C, D, I, G, S, L, J, H)$$

SUMMING OUT



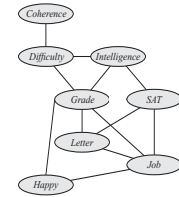
$$\begin{aligned} p(J) &= \sum_{L,S,G,H,I,D,C} p(C, D, I, G, S, L, J, H) \\ &= \sum_{L,S,G,H,I,D,C} \psi_C(C) \psi_D(D, C) \psi_I(I) \psi_G(G, I, D) \psi_S(S, I) \psi_L(L, G) \\ &\quad \times \psi_J(J, L, S) \psi_H(H, G, J) \\ &= \sum_{L,S} \psi_J(J, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \sum_I \psi_S(S, I) \psi_I(I) \\ &\quad \times \sum_D \psi_G(G, I, D) \sum_C \psi_C(C) \psi_D(D, C) \end{aligned}$$

SUMMING OUT



$$\begin{aligned} p(J) &= \sum_{L,S} \psi_J(J, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \sum_I \psi_S(S, I) \psi_I(I) \\ &\quad \times \sum_D \psi_G(G, I, D) \sum_C \psi_C(C) \psi_D(D, C) \end{aligned}$$

SUMMING OUT



$$\begin{aligned} p(J) &= \sum_{L,S} \psi_J(J, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \sum_I \psi_S(S, I) \psi_I(I) \\ &\quad \times \sum_D \psi_G(G, I, D) \sum_C \psi_C(C) \psi_D(D, C) \end{aligned}$$

Temporary factors

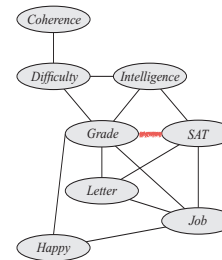
$$\tau'_1(C, D) = \psi_C(C) \psi_D(D, C)$$

$$\tau_1(D) = \sum_C \tau'_1(C, D)$$

$$\begin{aligned}
& \sum_L \sum_S \psi_J(J, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \sum_I \psi_S(S, I) \psi_I(I) \underbrace{\sum_D \psi_G(G, I, D) \sum_C \psi_C(C) \psi_D(D, C)}_{\tau_1(D)} \\
& \sum_L \sum_S \psi_J(J, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \sum_I \psi_S(S, I) \psi_I(I) \underbrace{\sum_D \psi_G(G, I, D) \tau_1(D)}_{\tau_2(G, I)} \\
& \sum_L \sum_S \psi_J(J, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \sum_I \psi_S(S, I) \psi_I(I) \underbrace{\tau_2(G, I)}_{\tau_3(G, S)} \\
& \sum_L \sum_S \psi_J(J, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \underbrace{\tau_3(G, S)}_{\tau_4(G, J)} \\
& \sum_L \sum_S \psi_J(J, L, S) \sum_G \psi_L(L, G) \tau_4(G, J) \underbrace{\tau_3(G, S)}_{\tau_5(J, L, S)} \\
& \sum_L \sum_S \psi_J(J, L, S) \underbrace{\sum_G \psi_L(L, G) \tau_4(G, J) \tau_3(G, S)}_{\tau_6(J, L)} \\
& \sum_L \underbrace{\sum_S \psi_J(J, L, S) \tau_6(J, L)}_{\tau_7(J)}
\end{aligned}$$

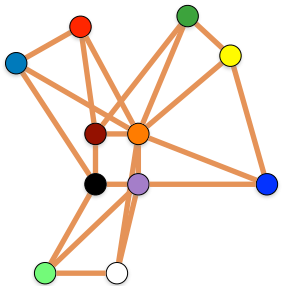
THE ENTIRE SEQUENCE

$$\begin{aligned}
& \sum_L \sum_S \psi_J(J, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \underbrace{\sum_I \psi_S(S, I) \psi_I(I) \tau_2(G, I)}_{\tau_3(G, S)} \\
& \sum_L \sum_S \psi_J(J, L, S) \sum_G \psi_L(L, G) \underbrace{\sum_H \psi_H(H, G, J) \tau_3(G, S)}_{\tau_4(G, J)} \\
& \sum_L \sum_S \psi_J(J, L, S) \sum_G \psi_L(L, G) \tau_4(G, J) \underbrace{\tau_3(G, S)}_{\tau_5(J, L, S)} \\
& \sum_L \underbrace{\sum_S \psi_J(J, L, S) \tau_5(J, L, S)}_{\tau_6(J, L)} \\
& \sum_L \underbrace{\tau_6(J, L)}_{\tau_7(J)}
\end{aligned}$$



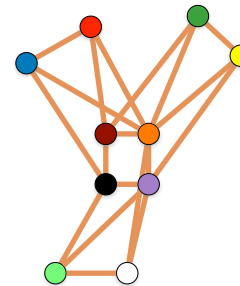
Fill in edge between two vertices in a "temporary factor"

A FILL-IN EDGE



ALTERNATIVE DEFINITION OF WIDTH

Elimination order of G – ordering of $V(G)$
 v_1, \dots, v_n
 It defines a sequence of graphs $G = G_0, \dots, G_n$
 where $G_i := G_{i-1} \vee_i \cup \{(u, w) : u, w \in N_{G_{i-1}}(v_i)\}$
 (i.e., we add edges between all neighbours)
 width of order = (max clique size in $u_i G_i$) - 1
 = $\max_i \text{degree of } v_i \text{ in } G_i$
 width of G = min width of order



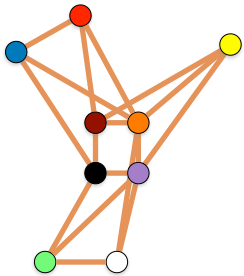
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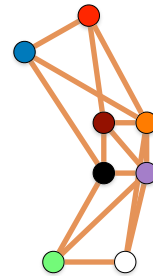
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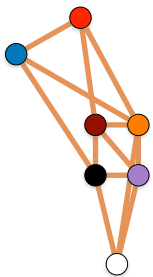
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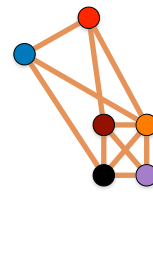
ALTERNATIVE DEFINITION OF WIDTH

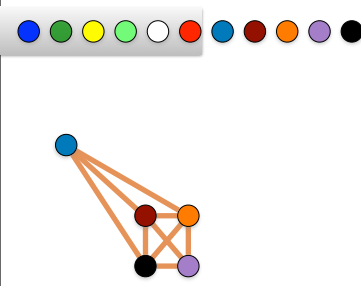
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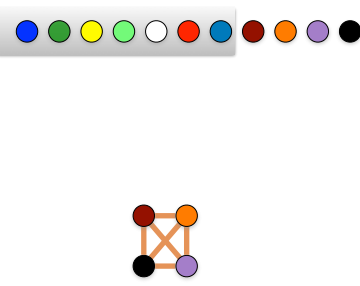
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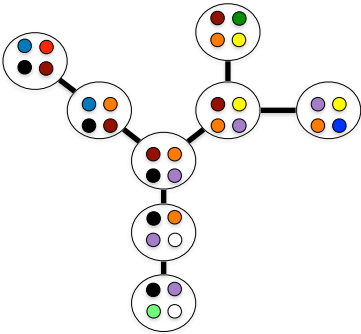
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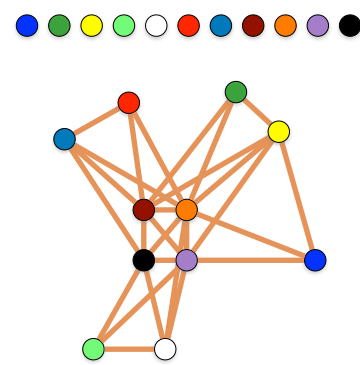
JUNCTION TREE

Definition junction tree

- ★ Each vertex of G in some bag
- ★ Each edge of G in some bag
- ★ Each vertex of G induce a subtree (running intersection property)
- ★ Width is (Size of largest bag) - 1

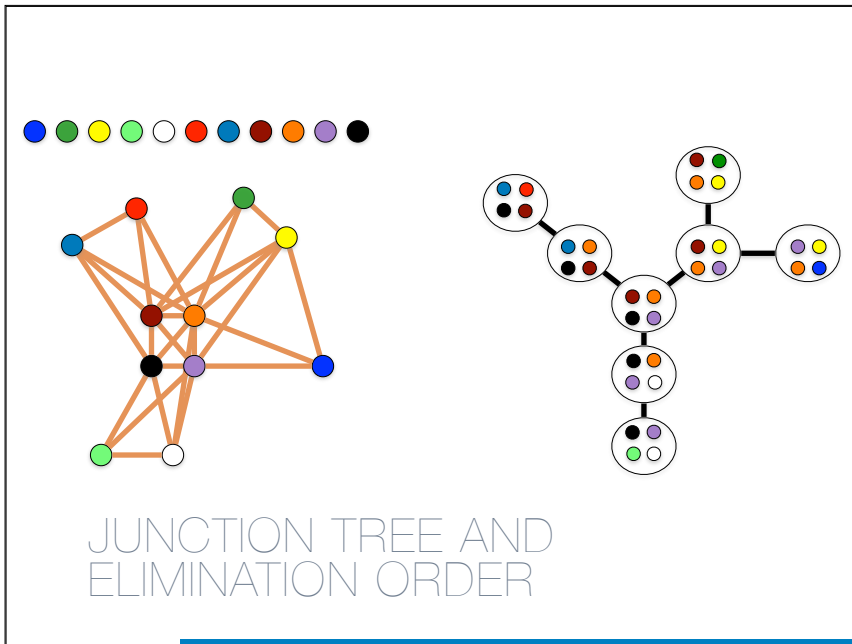
T,B junction tree





ALTERNATIVE DEFINITION OF WIDTH

A graph has a junction tree of width k if and only if it has a width k elimination order
 (i.e., eliminated vertices have at most k neighbours when eliminated).



COMPLEXITY OF VERTEX ELIMINATION

$$\sum_L \sum_S \psi_j(A, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \sum_T \psi_T(S, T) \psi_T(T, G, I)$$

$$\sum_L \sum_S \psi_j(A, L, S) \sum_G \psi_L(L, G) \sum_H \psi_H(H, G, J) \underbrace{\psi_T(S, T) \psi_T(T, G, I)}_{\tau_1(G, S)}$$

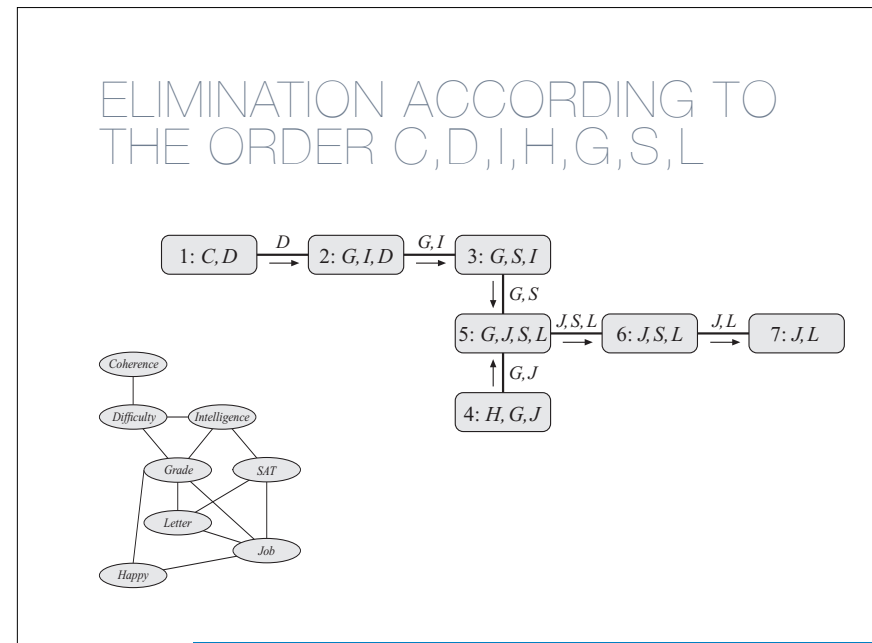
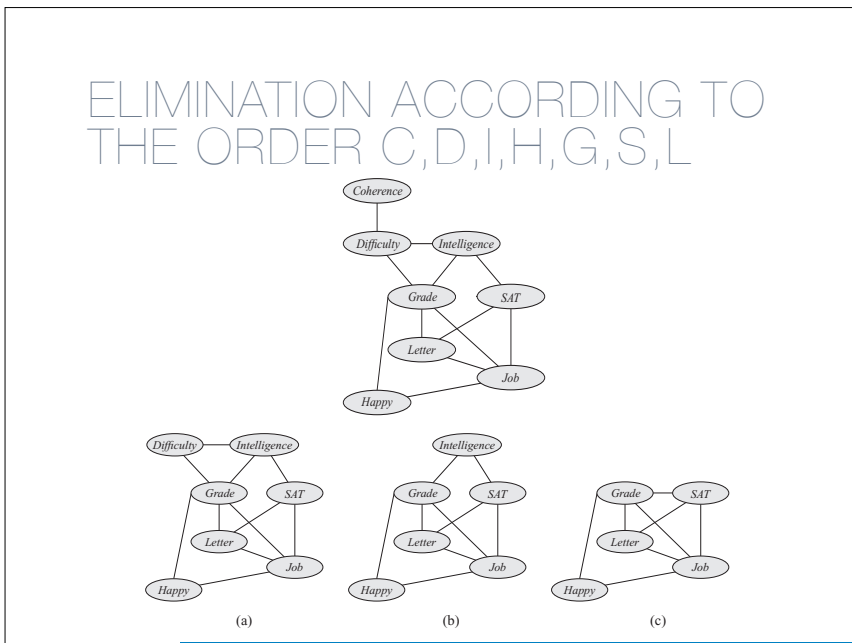
$$\sum_L \sum_S \psi_j(A, L, S) \sum_G \psi_L(L, G) \underbrace{\sum_H \psi_H(H, G, J)}_{\tau_2(G, J)} \underbrace{\psi_T(S, T) \psi_T(T, G, I)}_{\tau_3(G, S)}$$

$$\sum_L \sum_S \psi_j(A, L, S) \sum_G \psi_L(L, G) \tau_1(G, J) \tau_3(G, S)$$

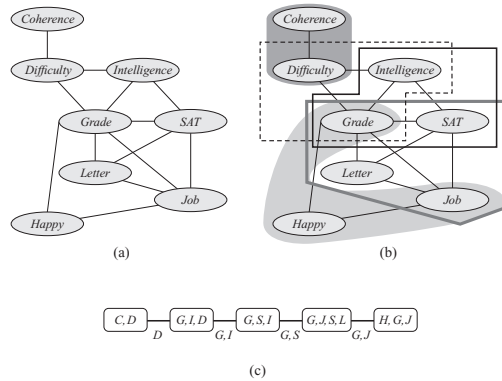
$$\sum_L \sum_S \psi_j(A, L, S) \tau_1(L, S) \tau_3(L, S)$$

$$\sum_S \tau_1(L, S) \tau_3(L, S)$$

- If the width is w
- Time $O(|V(G)| 2^w)$ for binary
- For categorical with C classes, $O(|V(G)| C^w)$

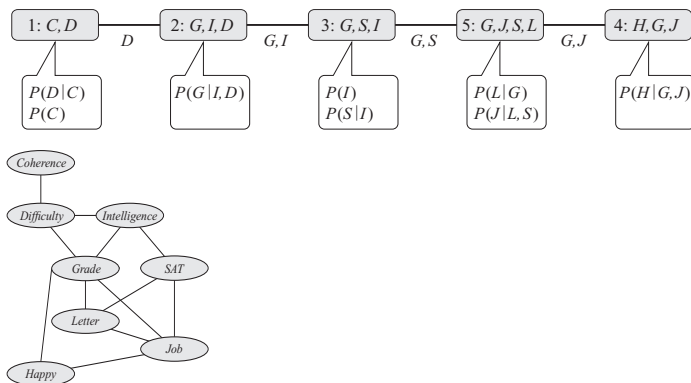


INDUCED GRAPH AND JUNCTION TREE



THE END

USING THE SIMPLER ELIMINATION & JUNCTION TREE



MESSAGE PASSING

