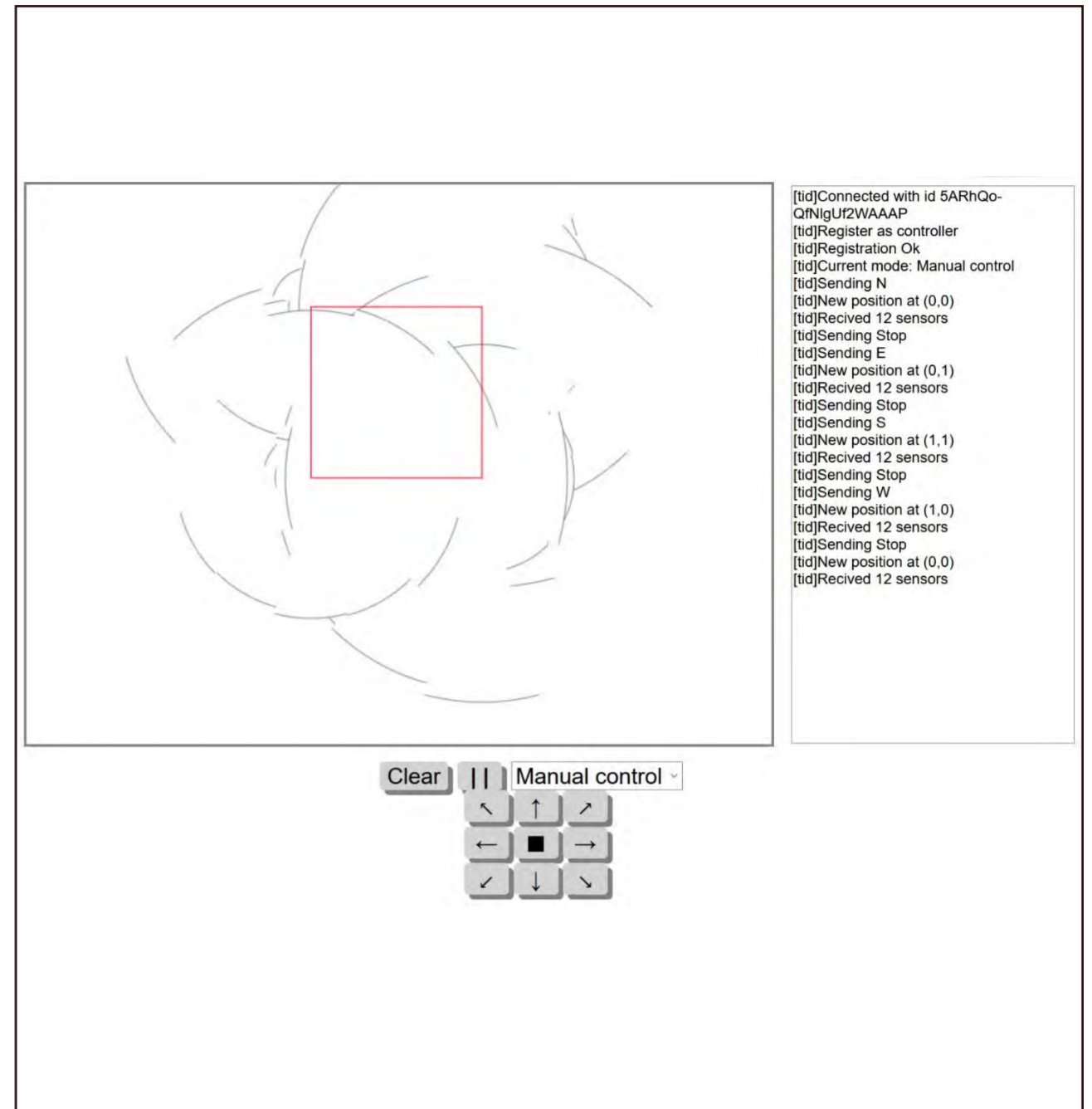


# Omnidirectional Robot

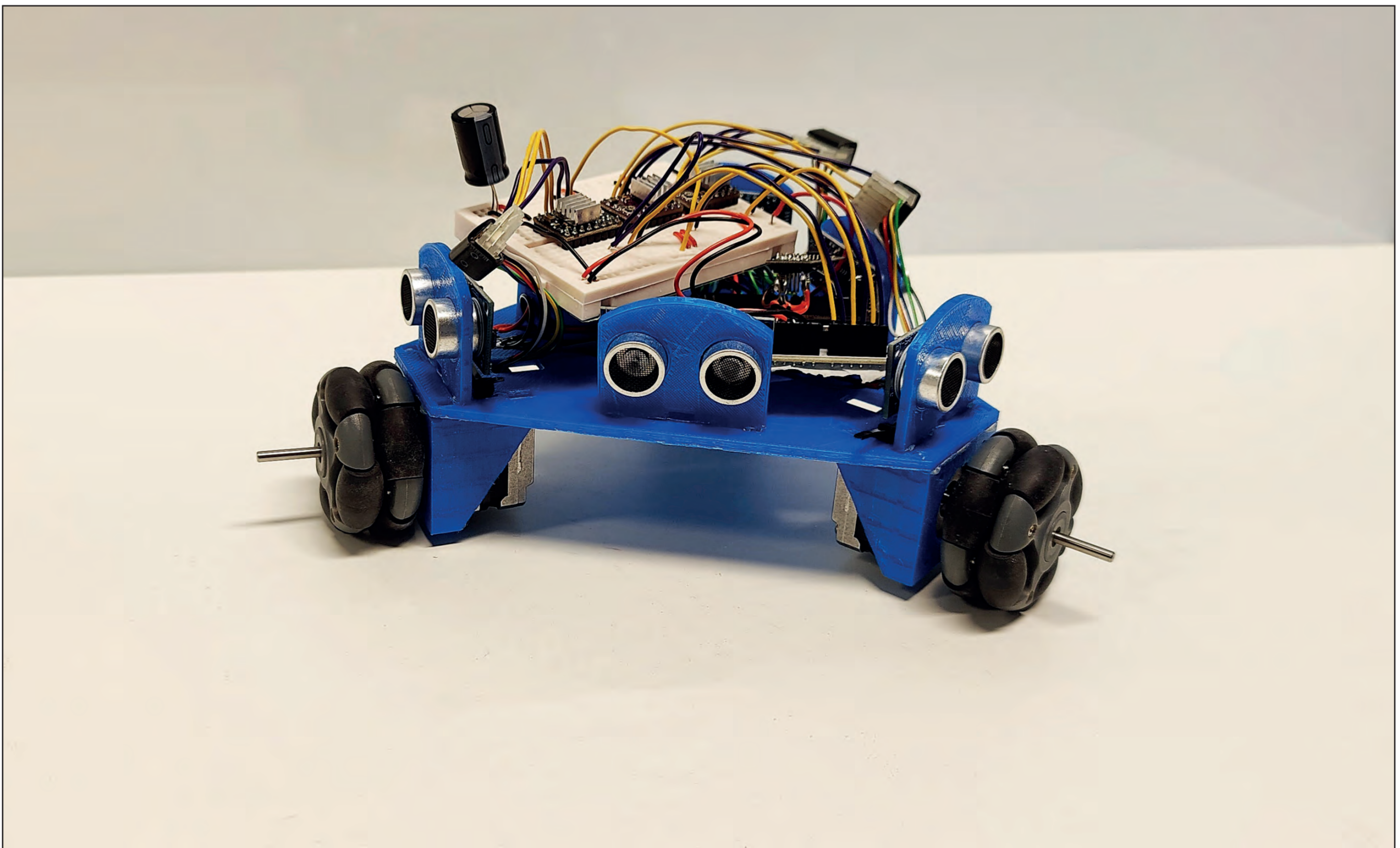
## Self driving and mapping robot



CAD render of the robot



The map with controls for the robot



Final prototype

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