

P.E.G.A.S

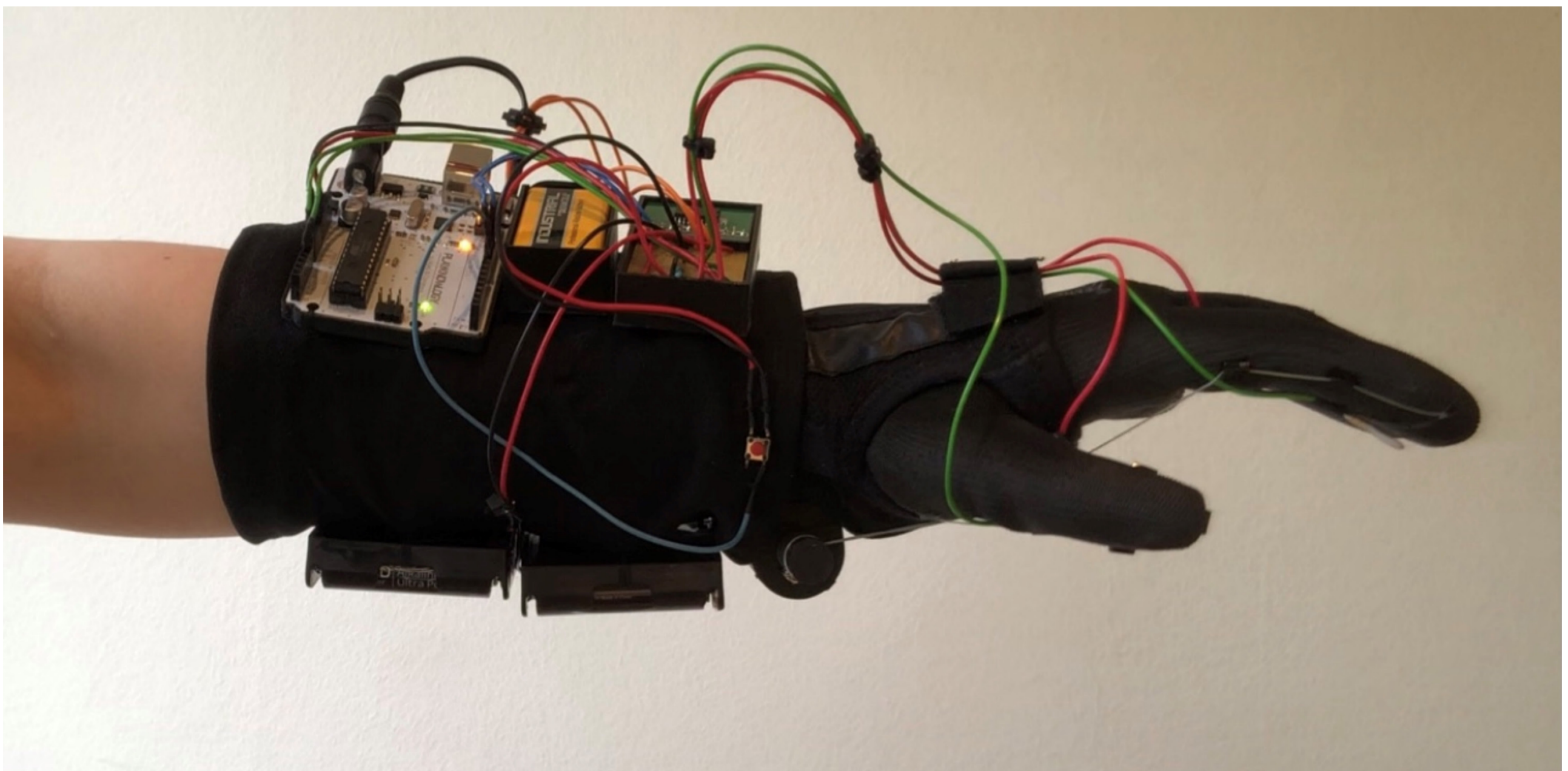
Powered Exoskeleton Grip Amplifying System



Palmar side of the final prototype.



Dorsal side of the final prototype.



Side view of the final prototype.

P.E.G.A.S is an exoskeleton that steers and controls the index finger and the thumb with the purpose to enhance the grip strength. The prototype is completely portable, lightweight and aids the user in activities of daily living.

Malin Dyberg
malindy@kth.se

Elvira Troillet
elvirata@kth.se



KTH Industriell teknik
och management