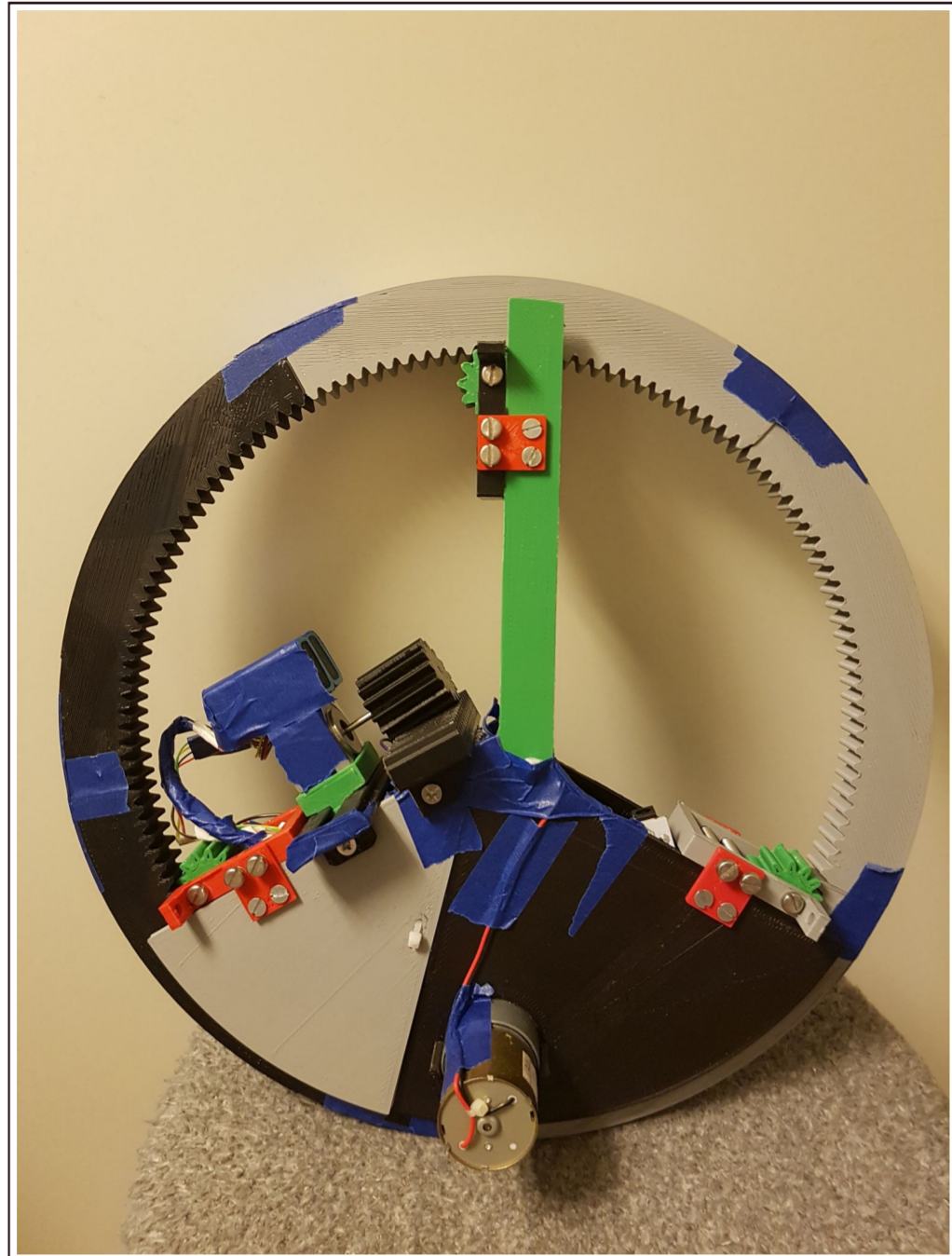
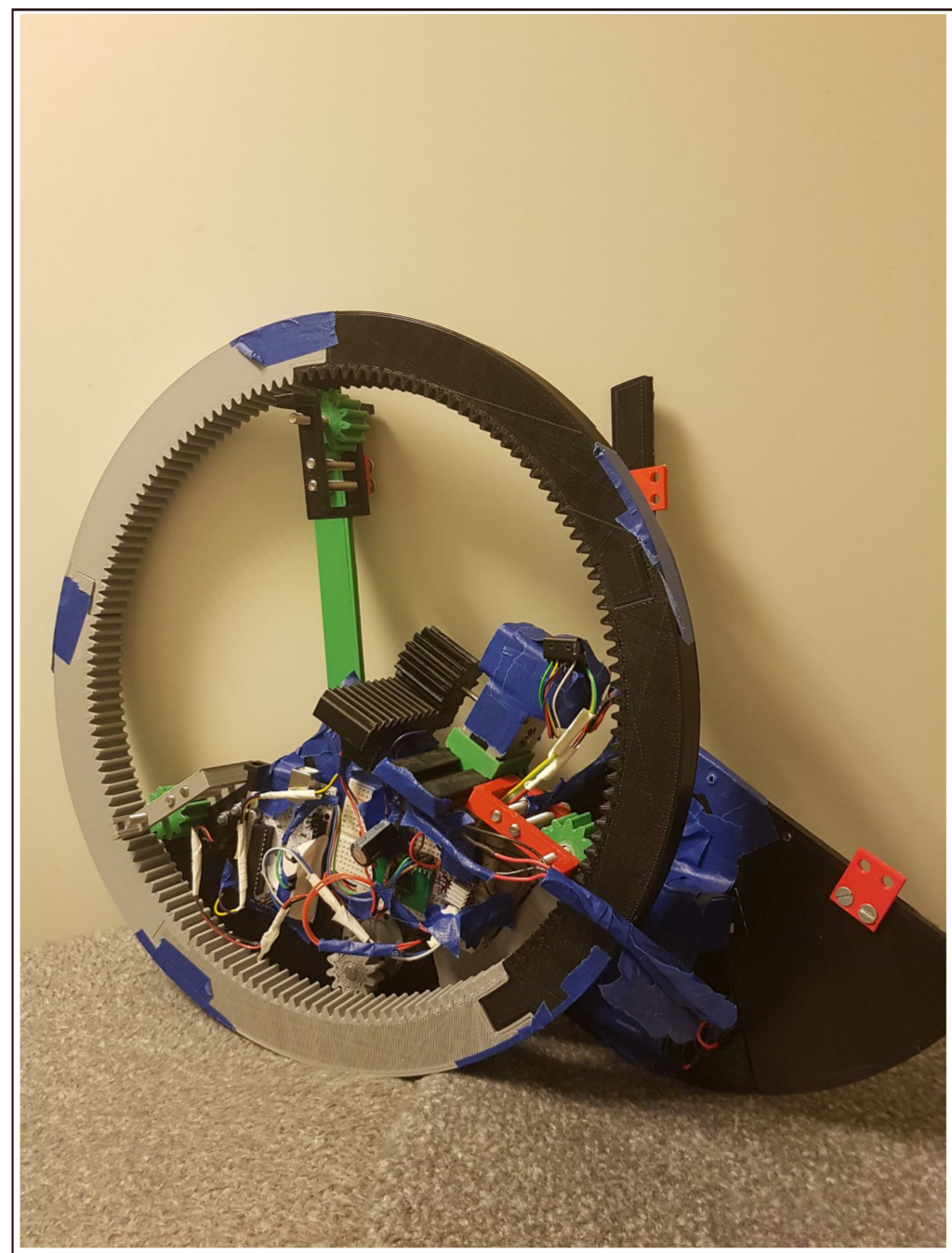


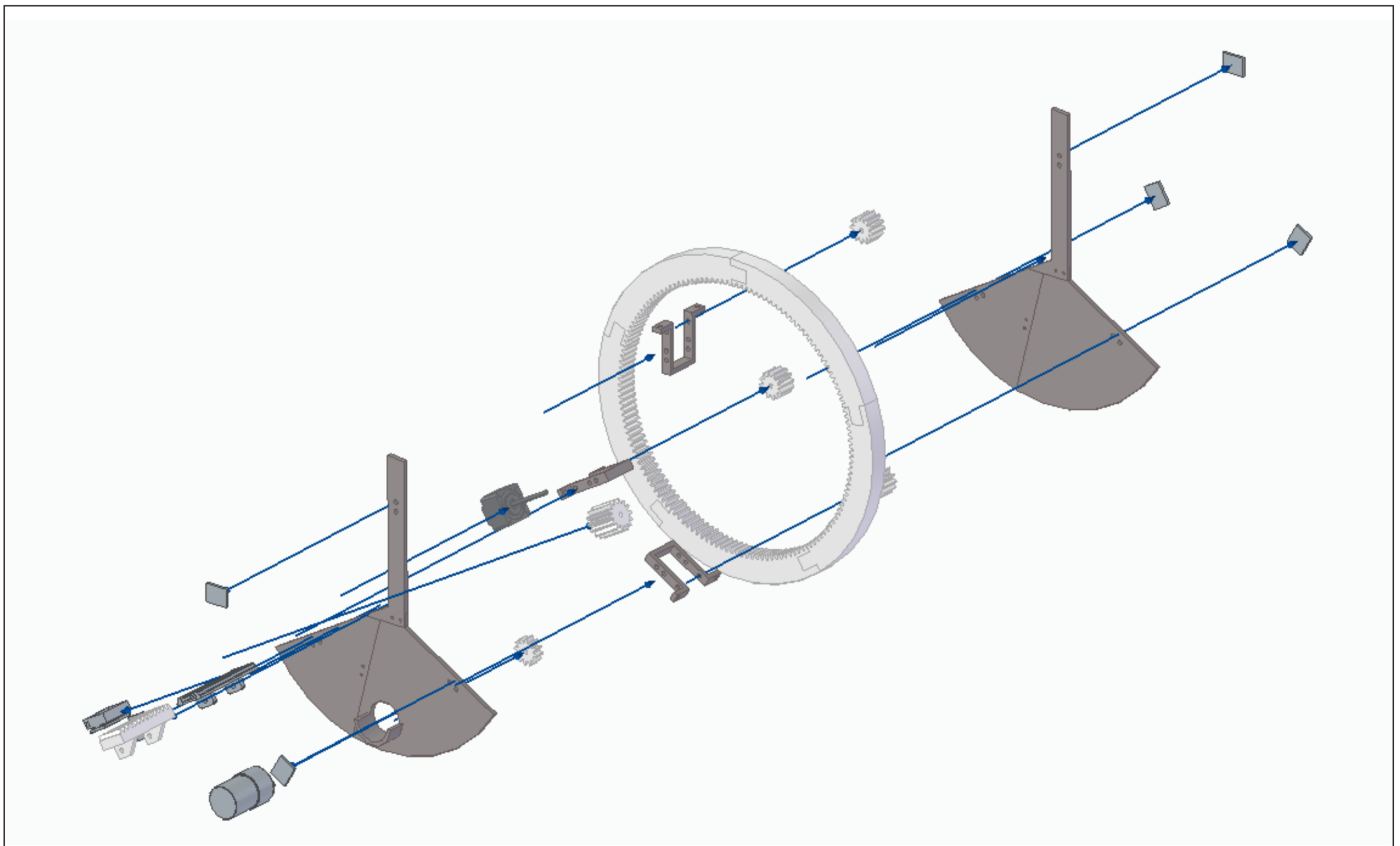
# Balancing a Monowheel with a PID controller



Finished prototype seen from the side.  
The balancing improved the average time  
the wheel was balanced with 17%.



Inside of the monowheel with electronics.  
Components used were DC- and Stepper  
motors and an accelerometer.



Exploded view of CAD model for the monowheel.

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