## Curriculum vitae

Basic Information	Rolf <u>Isaac</u> Skog Date of birth: 1981-06-15	<i>Voice:</i> $+46$ 708186805 <i>E-mail:</i> skog@kth.se	
CURRENT POSITIONS	KTH Royal Institute of Technology		
	Associate Professor	May. 2024 to present	
	• Associate Professor in Communication Systems at KTH Royal Institute of Technology.		
	S3 Research AB		
	<ul><li>Founder</li><li>R&amp;D within signal processing a</li></ul>	Jan. 2019 to present and machine learning.	
	FOI, Swedish Defense Research	Agency	
	<ul><li>Adjunct Senior Researcher</li><li>Signal processing research for u</li></ul>	Jan. 2019 to present underwater surveillance.	
	Nordic Institute of Navigation		
	<ul><li>Board member</li><li>Non-profit organisation for protion.</li></ul>	Mar. 2017 to present fessionals working within the field of naviga-	
Education	KTH, Royal Institute of Technology, Stockholm, Sweden		
	Docent, Signal Processing (2015) Ph.D., Signal Processing (2010)		
International Experience	WUSTL, Washington University in St. Louis		
	Visiting Scholar	Aug. 2014 & Aug. 2015	
	• Guest researcher at the Integrated Signal Processing in Research and Educa- tion Lab, Dept. Electrical & System Engineering, Washington University		
	IISc, Indian Institute of Science		
	Visiting Scholar	Sept. 2011 to Jan. 2012	
	• Guest researcher at the Statistical Signal Processing Lab, Dept. of Electrical Communication Engineering, Indian Institute of Science		
	UoC, University of Calgary		
	Visiting Scholar	Feb. 2009 to Jul. 2009	
	• Guest researcher at the Mobile Multi-Sensor Systems Research Team at the University of Calgary		
Research projects	Ongoing research projects		
	<ul> <li>Tensor-field based localization, Founded by Swedish Research Council (VR), 2021</li> <li>– onward. (PI)</li> </ul>		
	• Joint Sensing, Localization, and Communication for Next Generation Autonomous Underwater Systems, Founded by WASP, 2022 – onward. (PI)		
	• Complex Acoustic Surveillance and Tracking (COAST), conducted together with FOI Swedish Defense Research Agency. Founded by CENIIT, 2019 – onward. (PI)		

	• Distributed Learning of Augmented State-Space Models, Founded by WASP, 2024 – onward. (Co-PI)		
	<ul> <li>Cooperative Autonomous Air and Surface System for Underwater Surveillance in Complex Ocean Environments, Founded by WASP, 2024 – onward. (Co-PI)</li> <li>Integrated Sensing and Acoustic Communication (ISAAC) Founded by KTH</li> </ul>		
	2024 – onward. (PI)		
PhD students	Current and previous PhD students		
	<ul> <li>Ashwani Koul, LiU, main supervisor, ongoing.</li> <li>Chuan Huang, LiU, main supervisor, ongoing.</li> <li>Daniel Bossér, LiU, main supervisor, ongoing.</li> <li>Sebastian Karlsson, LiU, co-supervisor, ongoing.</li> <li>Anton Kullberg, Ph.D. Automatic Control, co-supervisor, LiU, 2024.</li> <li>Magnus Malmström, Ph.D. Automatic Control, co-supervisor, LiU, 2023.</li> <li>Håkan Carlsson, Ph.D. Signal Processing, co-supervisor, KTH, 2022</li> <li>Johan Walhström, Ph.D. Signal Processing, co-supervisor, KTH, 2017.</li> </ul>		
PUBLICATIONS AND PATENTS	Publications and patents		
	Summary of publication output:		
	<ul> <li>35 journal publications</li> <li>51 international conference papers</li> <li>4 patents</li> <li>5272 citations (h-index 33)</li> </ul>		
Awards	Scientific awards and token of excellence		
	• Listed among the top 2% most cited scientists in the world according to Elsevier RV and Stanford University <sup>1</sup> .		
	<ul> <li>Editor for the IEEE Journal on Indoor and Seamless Positioning and Navigation.</li> <li>Best Survey Papers Award<sup>2</sup> (2000–2009), IEEE Transactions on Intelligent Transportation Systems, 2013.</li> </ul>		
	• 2 <sup>nd</sup> Best Paper Award. A. Kullberg, I. Skog and G. Hendeby, <i>Iterated Filters</i> for Nonlinear Transition Models, 26th Int. Conf. on Information Fusion, 2023.		
	• 2 <sup>nd</sup> Best Paper Award. D. Bossér, G. Hendeby, M. L. Nordenvaad and I. Skog, A Statistically Motivated Likelihood for Track-Before-Detect, Int. Conf. on Mul- tisensor Fusion and Integration for Intelligent Systems, 2022.		
	• Co-creator and developer of the OpenShoe foot-mounted inertial navigation plat- form, used by researchers and companies in more than 20 countries. Retailed by GT Silicon, India, with +400 units sold.		
	• Co-creator and developer of the tactical locator (TOR) system, a full scale demonstration system for infrastructure-free positioning and tracking of fire fighters inside buildings. Awarded the best demonstration award at the IEEE Indoor Positioning and Indoor Navigation (IPIN) conference, Busan, Korea 2014.		
	• Developer of the signal processing and machine learning algorithms for SafeLine Sweden AB IoT system for predictive maintenance of elevator systems <sup>3</sup> .		
	<sup>1</sup> See database at https://elsevier_digitalcommonsdata_com/datasets/htchvbtzuu/5		

<sup>&</sup>lt;sup>•</sup>See database at https://elsevier.digitalcommonsdata.com/datasets/btchxktzyw/5 <sup>2</sup>The Top and the Best: Toward Excellence in ITS Research and Development, *IEEE Trans. on Intell. Transp. Syst.*, vol. 14, no. 3, Sep. 2013. <sup>3</sup>https://www.safeline-group.com/sv/produkter/safeline-orion/safeline-orion/ safeline-orion